



DP OPERATIONS GUIDANCE

**PREPARED THROUGH THE DYNAMIC POSITIONING
COMMITTEE OF
THE MARINE TECHNOLOGY SOCIETY
TO AID IN THE SAFE AND EFFECTIVE
MANAGEMENT OF DP OPERATIONS**

**PART 2
APPENDIX 1 - DP MODUS**

APRIL 2021

This Dynamic Positioning Guidance was created by the Dynamic Positioning Committee of the Marine Technology Society.

The guidelines have been developed from regulations, codes, guidance and industry practice existing at the time of publication, and their purpose is to aid in the safe management of DP operations. This publication was designed and intended as a resource for dynamic positioning professionals. For any other use beyond personal, research or educational purposes, please contact the Marine Technology Society.

All rights reserved © Marine Technology Society.

DISCLAIMER AND LIMITATION OF LIABILITY

The information presented in this publication of the Dynamic Positioning Committee of the Marine Technology Society (“DP Committee”) is made available for general information purposes without charge. The DP Committee does not warrant the accuracy, completeness, or usefulness of this information. Any reliance you place on this publication is strictly at your own risk. We disclaim all liability and responsibility arising from any reliance placed on this publication by you or anyone who may be informed of its contents.

IN NO EVENT WILL THE DP COMMITTEE AND/OR THE MARINE TECHNOLOGY SOCIETY, THEIR AFFILIATES, LICENSORS, SERVICE PROVIDERS, EMPLOYEES, VOLUNTEERS, AGENTS, OFFICERS, OR DIRECTORS BE LIABLE FOR DAMAGES OF ANY KIND UNDER ANY LEGAL THEORY, ARISING OUT OF OR IN CONNECTION WITH YOUR USE OF THE INFORMATION IN THIS PUBLICATION, INCLUDING BUT NOT LIMITED TO, PERSONAL INJURY, PAIN AND SUFFERING, EMOTIONAL DISTRESS, LOSS OF REVENUE, LOSS OF PROFITS, LOSS OF BUSINESS OR ANTICIPATED SAVINGS, LOSS OF USE, LOSS OF GOODWILL, LOSS OF DATA, AND WHETHER CAUSED BY TORT (INCLUDING NEGLIGENCE), BREACH OF CONTRACT OR OTHERWISE, EVEN IF FORESEEABLE.

THE FOREGOING DOES NOT AFFECT ANY LIABILITY WHICH CANNOT BE EXCLUDED OR LIMITED UNDER APPLICABLE LAW.

CONTENTS

SECTION	PAGE
1	8
PART 2	
1.1	8
1.2	8
1.3	8
2	11
DP OPERATIONAL DOCUMENTATION	
2.1	11
3	17
THEMES	
3.1	17
3.2	17
3.3	18
3.4	20
3.5	22
3.6	23
3.7	24
3.8	25
3.9	25
3.10	26
3.11	32
3.12	33
3.13	34
3.14	36
3.15	37
3.16	39
3.17	40
3.18	42
3.19	43
3.20	43
3.21	44
3.22	45
3.23	48
3.24	49
3.25	49
3.26	50
3.27	52
3.28	53
3.29	55
4	57
ABBREVIATIONS	
5	58
INTERVENTION – ROLE OF THE DPO AND ENGINEER	
5.1	58
5.2	59

TABLES

Table 2-1	Recommended Documentation	11
Table 3-1	DP Equipment Class Operational Reference	17
Table 3-2	Recommended DP Control Modes	34
Table 3-3	Critical Activity Mode (CAM or TAM) – Outline	46
Table 3-4	Well Specific Operating Guidelines - Outline	47
Table 3-5	DP Bridge Crew	55

APPENDICES

APPENDIX A	REFERENCE STANDARDS/ GUIDELINES
APPENDIX B	DP FOOTPRINT PLOTS – WORKED EXAMPLES
APPENDIX C	ANNUAL DP TRIALS TEST TABLE BLANK – DP MODU
APPENDIX D	EXAMPLE OF CAM AND WSOG

PREFACE TO REVISION 3 (2021)

This guidance document has been updated to Revision 3 in 2021. Revision 3 reflects developments in the DP sector that have occurred since the publication of Version 2 in 2012. Revision 3 refers to and acknowledges the value of other operational and technical DP guidance documents that have been published since 2012.

In that period the MTS DP Committee has published a raft of new guidance, in particular in the TECHOP Series which target many areas of concern in the DP sector and in the comprehensive and detailed 'DP Vessel Design Philosophy Guidelines'. Although the majority of these new MTS publications are focused on design and on purely technical matters, they are relevant to the safe operation of DP vessels and merit recognition and reference in this document.

In the same four year period IMCA has revised a number of its own well known publications, in particular, IMCA M166 "Guidance on FMEA" and IMCA M103 'Guidelines for the Design and Operation of DP Vessels'. IMCA has also published new guidance that more directly reflects the intent and content of MTS publications. This is seen in IMCA M212 'Example of an Annual DP Trials Report', IMCA M220 'Guidance on Operational Activity Planning' and IMCA M225 'Example Redundancy Concept and Annual DP Trials for a DP Class 3 Construction Vessel'.

Revision 3 also recognises the recent changes that have taken place in the training and certification of DPOs. Whereas in 2012 the Nautical Institute DPO Certification Scheme was the only one available, in 2021 there are now two alternative schemes, one developed and managed by the OSVDPA and the other by DNVGL SeaSkill.

Revision 3 follows the same basic outline and themed approach as in the previous two versions so it should be familiar to readers and to those who have consulted it for DP operational guidance.

The intent of the guidance remains to support incident free DP operations in the international offshore oil and gas sector.

PREAMBLE

This document has been generated by the MTS DP Technical Committee and has been provided to industry as a guidance document for the safe and effective conduct and management of DP operations.

This document is not meant to replace any rules, regulations or owners' operational manuals. It is a compilation of existing guidance and practices gleaned from various sources in industry. It refers to standards and guidance used within the industry and draws attention to them. It also incorporates additional information gleaned from experience and document/ standards not in the public domain,

This is not intended to be an all-encompassing document covering all aspects of DP operations. It focuses on a number of important DP operational themes, which, if effectively managed, will result in safer DP operations and a reduction in exposure to DP related incidents.

The guidance provided in this document is not directed at any particular category of DP operation or DP vessel. It is intended to apply to any DP operation undertaken by any type and class of DP vessel operating in support of offshore oil and gas activities. Examples include MODUs, ships, construction and logistics vessels where dynamic positioning is used for, or aiding, station keeping.

Layout of the Document

This document consists of two parts. Part 1 contains guidance on the management of DP. Part 2 contains DP operational guidance. Part 2 consists of three Appendices:

- Part 2 Appendix 1 – DP MODUs
- Part 2 Appendix 2 – DP Project / Construction Vessels
- Part 2 Appendix 3 – DP Logistics Vessels ¹

This has been done to facilitate ease of use by these groups taking into account the uniqueness of their particular activity.

Whilst station keeping using DP is the common mode for all three groups the activity that they are undertaking may need varying emphasis on different themes.

This Part 2 contains both the content of Part 1 as well as Part 2. Part 1 content is in regular Arial font size 11, whereas Part 2 content of is in *Arial italics font size 10*. This clearly identifies the Part 2 content at the same time as putting it into context with Part 1 without having to refer back to a separate Part 1 document.

THIS DOCUMENT IS PART 2, APPENDIX 1 (DP MODUs) OPERATIONAL GUIDANCE

¹ When logistics vessels are used as platforms to carry out project/ construction activities they should follow the guidelines for project/ construction vessel/ barges.

1 PART 2

1.1 PHILOSOPHY

1.1.1 This document was compiled with the following objectives:

- Manage, mitigate and reduce the exposure to, and potential of, DP related incidents.
- Identify themes that need to be managed.
- Provide a list of reference documents that address themes, whilst acknowledging that existing referenced documents do not identify all elements adequately when viewed in isolation.

1.1.2 Provide operational guidance to assist owners/ operators and crews of DP vessels and MODUs to execute DP operations safely and without incident.

1.2 SCOPE

1.2.1 Part 2 provides operational guidance on the themes identified in Part 1.

1.2.2 The themes that have been identified and addressed in this document are:

1. DP Class
2. FMEA/ FMECA
3. DP Capability
4. Position Reference Systems And Sensors
5. Required Modes
6. Trials And Checklists
7. Operation Manuals
8. Activity and Operational Planning
9. Communications
10. DP Planned Maintenance
11. DP Incidents
12. Reporting And Record Keeping
13. Competency
14. Manning
15. *Operator Intervention – DPOs and Engineers (Part 2 only).*

Note Item 15 has been added to the fourteen identified themes and is addressed separately in subsection 5.

1.3 DEFINITIONS

1.3.1 DP System

The DP system means the complete installation necessary for dynamically positioning a vessel, comprising the following subsystems; power system (power generation and power management), thruster system and the DP control system.

1.3.2 DP Control System

The DP control system consists of all control components and systems, hardware and software necessary to dynamically position the vessel. The DP control system comprises computer systems, sensors, display systems, position reference systems and associated cabling and routing.

1.3.3 **Worst Case Failure**

The Worst Case Failure (WCF) is the identified single failure mode in the DP system resulting in maximum effect on DP capability as determined through an FMEA study.

1.3.4 **Worst Case Failure Design Intent**

The Worst Case Failure Design Intent (WCFDI) describes the minimum amount of propulsion and control equipment remaining operational following the worst case failure. The WCFDI is used as the basis of design. Single fault tolerance is to be achieved by the provision of redundant systems.

1.3.5 **Redundancy Concept**

The Redundancy Concept is the means by which the Worst Case Failure Design Intent is achieved.

1.3.6 **Industrial Mission**

The primary operational role of the vessel, typically applicable to MODUs and Project and Construction vessels, e.g. Pipe-lay/Heavy-lift. The industrial mission for logistics vessels is to support logistics.

1.3.7 **Critical Activity Mode (CAM)** ²³

Critical Activity Mode is the DP system configuration that provides the highest level of station keeping integrity.

1.3.8 **Activity Specific Operating Guidelines (ASOG)**

Activity Specific Operating Guidelines set out the operational, environmental and equipment performance limits considered necessary for safe DP operations while carrying out a specific activity. The table also sets out various levels of operator action as these limits are approached or exceeded. The ASOG will vary depending on the activity and are unique to that activity.

1.3.9 **Well Specific Operating Guidelines (WSOG)**

See above definition of ASOG. Where DP MODUs are carrying out well activities the term WSOG is generally used. Other terms in use are Well Specific Operating Criteria (WSOC) and Well Specific Operating Plan (WSOP).

1.3.10 **Task Appropriate Mode (TAM)** ⁴

Task Appropriate Mode is a defined DP system configuration which strives to offer station keeping integrity and fault tolerance but not to the same extent as CAM. TAM is a risk based mode.

1.3.11 **Thruster and Generator Operating Strategy (TAGOS)**

A document that provides informed guidance, usually derived from a review of the DP FMEA and if necessary, validation from personnel knowledgeable about vessel specific information, on appropriate configurations of thrusters, generators and power distribution, and associated constraints, so as to enable correct choices to be made to provide optimum level of redundancy.

² CAM was previously referred to as SMO (Safe Mode Operation). The term “SMO” has been removed and replaced entirely by CAM. The term “SMO” is no longer considered suitable for use.

³ The term “CAMO” has been used synonymously with the “CAM” in previous versions of this document. It is also to be found in other guidance publications from other bodies. For the purposes of this version of the guidance the term in use is “CAM”.

⁴ Task Appropriate Mode (TAM) is not to be confused with Thruster Assisted Mooring (TAM).

1.3.12 DP Capability Plots

DP Capability Plots define by theoretical calculation the vessel's capability to maintain position in various environmental conditions, (i.e. wind, seastate and current) and, where appropriate, taking account of certain external forces, such as pipe tension and, in various thruster/ power configurations, including all thrusters running, loss of most effective thruster and following worst case failure.

1.3.13 DP Footprint Plots⁵

DP Footprint Plots⁶ are constructed, by observation onboard the vessel in real time conditions. The plots are of the vessel's DP station keeping performance and limitations in various environmental conditions (wind, seastate and current) and in various thruster/ power configurations, including all thrusters running, loss of most effective thruster and after worst case failure.

1.3.14 Time to Terminate (TTT)

Time to Terminate is calculated as the amount of time required in an emergency to physically free the DP vessel from its operational activity following a DP abort status and allowing it to be manoeuvred clear and to proceed to safety.

Examples: In the case of a DP drilling vessel this may be the time needed to release from the wellhead. For a DP diving vessel this may be the time needed for the diver(s) to return to the bell and make a seal so that the vessel can move clear. The Time to Terminate is not fixed for the duration of a DP operation but will vary according to the circumstances.

⁵ It is acknowledged that DP Footprint Plots for DP MODUs may be less relevant in comparison to DP vessels engaged in other activities.

⁶ Owing to their almost continuous work programs DP MODUs will rarely have the opportunity to record DP Footprint Plots for degraded thruster configurations.

2 DP OPERATIONAL DOCUMENTATION

2.1 GENERAL

2.1.1 It is recommended that DP vessel owners/ operators should maintain the documentation listed in the table below and should develop and implement associated processes for the purposes of:

- ensuring the safe and effective management of the vessel in DP.
- ensuring the technical suitability of the vessel for each DP activity it is required to carry out.
- determining the configuration for the mode of operation (Critical Activity Mode (CAM) and task appropriate mode (TAM)).
- understanding the vessel’s station keeping capabilities following the worst case failure.
- ensuring compliance with appropriate standards and guidelines.
- providing training and familiarization material to vessel crews.

2.1.2 See Table 2-1 Recommended Documentation. Current versions of the documents in the list below should be kept on board and, in addition, where feasible, at the shore based centres of technical management. Documents that have been superseded should be clearly marked and kept separate from current versions. Documents may be in electronic or, hard copy format or, both.

Further guidance relating to the documents listed below is given in appropriate sections later in this document.

Table 2-1 Recommended Documentation

No.	Document	Management Guidance	Operational Guidance
1	DP System FMEA or FMECA	To be kept up to date, incorporating all modifications and additions since original study, if not in the document itself, then by other traceable means. All records to be kept on board and onshore for shore-based management.	<i>Modifications and additions should be covered by a MOC process that triggers updating the FMEA.</i>
2	DP FMEA Proving Trials	To be conducted after commissioning to prove initial DP FMEA and at other times to prove modifications and additions to the DP system. Findings should be addressed in accordance with their criticality. All records to be kept on board.	<i>Modifications and additions that should be proven by testing include all those that have direct effect or, potential to affect the performance or redundancy of the DP system. This will include protective, detection and monitoring functions.</i>

No.	Document	Management Guidance	Operational Guidance
3	Annual DP Trials	To be conducted annually ⁷ to prove the DP system is fully functioning and well maintained and that the redundancy concept is intact. Findings should be addressed in accordance with their criticality. Previous trials reports and associated close out documentation to be kept on board.	<p><i>The tests in the Annual DP Trials should be designed to prove system redundancy, as defined in the DP FMEA, system and equipment performance and functionality, to validate repairs and preventive maintenance, to test the operation of protection and detection devices and their response so as to demonstrate that the vessel's DP system remains fit for purpose.</i></p> <p><i>The option exists for DP MODUs to carry out Annual DP Trials on an incremental basis in accordance with the IMCA M191.</i></p>
4	DP Capability Plots	Hard copy DP Capability Plots relevant to the vessel's areas of operations to be readily accessible to DPOs at the DP control location.	<p><i>Capability plots to be validated/ recalculated, as required, to ensure that they are suitable for the environmental conditions where the DP operations are to take place, in particular in respect of current speeds. This requirement to validate/ recalculate applies also in cases where DP vessel performance is affected by operational constraints imposed by the activity, such as in the case of a pipelay vessel with horizontal loads.</i></p>
5	DP Footprints ⁸	Hard copy DP Footprint Plots to be taken by DPOs.	<p><i>DP Footprint Plots should be taken regularly in various power/ thruster combinations, including fully intact and worst case failure and also in various environmental conditions.</i></p>
6	Service reports concerning the DP system	Complete history of service reports to be filed and kept on board.	<p><i>There should be a process where the open items are highlighted, risk assessed, tracked and closed out by a target date.</i></p>

⁷ It is recommended that Annual DP Trials are carried out on a specific occasion each year and within three months before or after the anniversary date of the vessel's initial DP FMEA Proving Trials.

⁸ It is acknowledged that DP Footprint Plots may be less relevant for DP MODUs than for other DP vessel types.

No.	Document	Management Guidance	Operational Guidance
7	Details of all DP related modifications and additions	<p>Records of all DP related modifications and additions to be kept on board complete with interface and testing information.</p> <p>See Note at end of table.</p>	<p>A structured FMEA and Proving Trials approach should be used to integrate modifications and additions into the existing DP system and its associated equipment.</p> <p>New and modified software should be subjected to a thorough validation process, especially to avoid the acceptance of erroneous values. Regression testing is recommended where software has been modified or interfaced to other software. Known instances as examples; pipe tensioner software that accepted a sudden increase of pipe tension from 100t to 300t (erroneous input), software for thruster control that increased the command to the thruster to match the faulty feedback.</p> <p>It is not enough to focus on the functionality of modifications and additions. It is equally important to fully understand the functional design spec and the dependencies and consequences of fault or failure.</p>
8	Vessel audit reports and DP audits and inspection reports.	Complete history of all audit reports, DP audits and inspection reports, including findings and close outs to be kept on board	There should be a process where the open items are highlighted, tracked and closed out.
9	DP Operations Manual	Vessel Specific DP Operations Manual ⁹ , to be readily accessible at the DP control location and used by the DPOs as a reference for conducting DP operations.	<p>It is recommended that owners/ operators develop a standardised table of contents for vessel specific DP Operations Manuals in their fleet.</p> <p>Modifications and amendments to the DP Operations Manual should be subject to MOC processes, including changes to vessel specific checklists.</p>
10	DP Incident Reports	Records of all DP station keeping and other DP related incidents to be kept on board, including investigation records and close outs.	All DP incidents should be investigated to an extent that reflects the potential consequences of the incident.

⁹ The vessel specific DP Operations Manual is additional to the DP control system manufacturer’s Operator Manual

No.	Document	Management Guidance	Operational Guidance
11	DP Mobilization/ DP Field Arrival/ Trials Procedures (Bridge and Engine Room)	Records of DP Mobilization Trials and DP Field Arrival Checklists to be kept on board for the period set by the owner/ operator and, where relating to a DP incident permanently stored in retrievable archives.	DP Trials and Checklists should be vessel specific and be developed from detailed information contained in the DP FMEA. They should confirm vessel performance, particularly following worst case failure, and that the vessel's DP system is set up properly and provides the required level of redundancy.
12	DP Location and Watchkeeping checklists (Bridge and Engine Room)	Records of all DP Location and Watchkeeping Checklists to be kept on board for the period set by the owner/ operator and, where relating to a DP incident, permanently stored in retrievable archives.	As above
13	DP related drills and emergency response drills	Records of DP related drills and emergency response drills to be kept on board in retrievable archives.	DP drills can be developed from fault and single point failure scenarios addressed in the vessel's DP FMEA. The drills should also cover extreme events that are outside the scope of the DP FMEA. The outcomes from these drills should be used in the development of DP emergency response procedures and used as training material for DP personnel. These records may be used in a cycle of continuous improvement.
14	DP fault log	Records of all faults related to the DP system to be kept on board permanently in retrievable archives.	DP faults should be recorded as soon as possible after they are discovered and action/ investigation taken appropriate to the potential consequences of the fault on the vessel's station keeping ability.

No.	Document	Management Guidance	Operational Guidance
15	DP Data Logging	Where the vessel has DP data logging facilities, electronic records should be kept on board for the period set by the owner/ operator and, where relating to a DP incident, permanently stored in retrievable archives.	<p>DP data loggers perform an important function in helping to determine root causes of faults or failures.</p> <p>It is recommended that a DP data logging function is included as part of the DP system design spec.</p> <p>DP data loggers should be commissioned and operational before DP system Customer Acceptance Trials (CAT) are carried out.</p> <p>The DP data logger should be incorporated in the CAM/TAM and running at all times when in DP. If not, this should trigger an Advisory condition, i.e. BLUE.</p> <p>There should be specific procedures for the operation and analysis of output from the DP data logger. This should include clear instructions on how and where the records are kept.</p> <p>Retention of data logging data should not be limited by time.</p>
16	DP alarm printer readouts	Hard copy records of the DP alarm printer readout to be kept on board for the period set by the owner/ operator and, where relating to a DP incident, permanently stored in retrievable archives.	Owners/ operators frequently require DP alarm printer readouts to be kept for the duration of each well and then destroyed, unless relating to a DP incident or contractual dispute.
17	DP familiarisation and competency records	All records relating to vessel specific DP familiarisation and competency for DPOs, engineers and electricians to be kept on board permanently in retrievable archives.	<p>Owners/ operators should implement an in-house DP competency assurance process for key DP personnel which is structured, systematic and progressive. It should be noted that DPO certification is only one element in the competency assurance process.</p> <p>Owners/ operators are recommended to make use of facilities and training programmes available to the DP sector, such as the Powersim program for advanced DPO training of power plant fault conditions, where DPOs are given detailed instruction and training in identifying and responding to power system faults. Examples include DPO intervention averting an underfrequency induced blackout on closed bus system by the DPO taking control of thrusters and biasing to increase load.</p>

No.	Document	Management Guidance	Operational Guidance
18	Résumés and vessel specific work records of all key DP personnel	Résumés of all key DP personnel, copies of certification and qualifications, records of DP watchkeeping hours to be maintained on board. Original DPO certificates and DP Log Books to be held by the DPOs onboard the vessel.	
19	CAM, TAM	Records of CAM and TAM configurations to be kept permanently on board and onshore, including all revisions and updates.	
20	ASOG (WSOG, WSOC, WSOP)	Records to be kept on board for the period set by the owner/ operator and, where relating to a DP incident, permanently stored in retrievable archives.	

Note Owners/ operators should keep adequate records and documentation relating to modifications and additions that could have an effect on the DP system, especially interfaces between equipment from different vendors. This is as relevant for equipment whose primary function lies outside the DP system, such as an Emergency Shutdown Systems (ESD), pipe tensioner systems and fire monitor systems as it is for DP equipment, such as propulsion, position references and sensors. All modifications and additions should be subjected to FMEA type analysis and undergo Proving Trials type testing.

3 THEMES

3.1 GENERAL

3.1.1 The themes in this Part 2 Appendix 1 of the MTS Guidance are addressed from a management and operational perspective.

3.2 DP CLASS

3.2.1 IMO MSC 645 “Guidelines for Vessels with Dynamic Positioning Systems is the base or foundation document for DP vessels.

3.2.2 It is recommended that DP vessels with the following DP equipment class notations be used for the following activities. These recommendations refer to minimum DP equipment class. owners, operators and charterers may opt for higher requirements.

Table 3-1 DP Equipment Class Operational Reference

Application on DP	Minimum Recommended DP Equipment Class (See Note 1 below)	Remarks
Drilling	2	
Diving	2	
Pipelay	2	
Umbilical Lay	2	
Lifting	2	
Accommodation	2	
Shuttle Offtake	2	
ROV Support (Open Water)	1	
ROV Support (Close Proximity - Surface/ Subsea)	2	
Floating Production	2	
Seismic and Survey vessels (Open water- outside 500 m zone)	**	Class in accordance with contractual requirements
Well Stim	2*	Vessels of lesser Class may be used with the appropriate structured risk identification and mitigation measures in place.
Logistics Operations	2*	Vessels of lesser Class may be used with the appropriate structured risk identification and mitigation measures in place.

NOTE 1 - The vessel’s DP system should be set up and operated in the identified Critical Activity Mode (CAM) configuration. However, on occasion and after a proper assessment of the risks, the vessel may be set up in accordance with the identified Task Appropriate Mode. (TAM)

Guidance Notes

A detailed risk analysis will be required if the vessel is to operate in a task appropriate mode (TAM). The detailed risk analysis should consider the consequences of loss of position relevant to the activity.

3.3 DP FMEA

- 3.3.1 The requirement for a DP FMEA has its origins in IMO MSC/Circ 645 (1994) "Guidelines for Vessels with Dynamic Positioning Systems"¹⁰. These benchmarking guidelines provide the foundation for all subsequent DP rules, regulations and guidance issued by Class and other industry bodies, such as IMCA and MTS.
- 3.3.2 The IMO Guidelines require all DP vessels to be subjected to survey and testing in accordance with IMO's specified guidelines. IMO requires initial and periodic complete survey and testing of all systems and components required to keep position after single failures associated with the vessel's assigned DP equipment class.
- 3.3.3 This IMO requirement has been interpreted by the DP community such that the survey requirement is met by a DP FMEA (or FMECA¹¹) and the testing requirement by DP FMEA Proving Trials.
- 3.3.4 The initial survey requirement is achieved by conducting a DP FMEA and the initial testing by DP FMEA Proving Trials. DP FMEA Proving Trials focus on proving that the WCFDI is not exceeded and that the failure effects are as expected. The trials may include once-only tests, such as HV short circuit testing, and exploratory tests designed to prove additional information about how the redundancy concept functions. Once the information has been obtained there should be no need to repeat those particular tests.
- 3.3.5 The IMO Guidelines also require periodic surveys at intervals not exceeding five years to ensure compliance with applicable parts of the guidelines and a complete test of all systems and components required to keep position after single failures associated with the assigned equipment class. This periodic requirement can be achieved in different ways, for example Annual DP Trials can include tests of systems and components necessary for maintaining the DP system's redundancy concept. It is not necessary to repeat the DP FMEA Proving Trials every five years.
- 3.3.6 In addition, compliance with IMO Guidelines requires survey and testing after defects are discovered and corrected and, after a DP related accident and, whenever significant repairs or alterations are carried out, so as to demonstrate full compliance with applicable parts of the guidelines.
- 3.3.7 The IMO Guidelines do not make clear distinction between vessels of different DP equipment class as far as application of the initial and periodic surveys and testing are concerned.
- 3.3.8 The vessel's DP FMEA and Proving trials should cover both CAM and TAM configurations. (This may involve the FMEA covering both open and closed bus tie configurations)
- 3.3.9 Definition: A FMEA is a systematic analysis of systems and sub-systems to a level of detail that identifies all potential failure modes down to the appropriate sub-system level and their consequences. A FMECA is an extension of an FMEA that adds a risk assessment of each failure mode to determine its criticality.

¹⁰ Refer to para 5.1.1.1 of IMO MSC/Circ 645 (1994)

¹¹ Unless expressly stated in this Guidance document a FMECA is interchangeable with an FMEA.

3.3.10 In addition to complying with the IMO Guidelines and the relevant DP rules of the vessel's Classification Society the DP FMEA should achieve the standards of detail and analysis contained in the following industry guidance:

- MTS DP Vessel Design Philosophy Guidelines Parts 1 and 2.
- MTS DP Committee's TECHOP Series of Guidance Documents. 12

– ¹² The TECHOP series of guidance documents is freely available from the MTS DP Committee website at <http://dynamic-positioning.com/documents/technical-and-operational-guidance-notes/>. The list below contains all the valid TECHOPs at time of preparing this document. Readers should consult the MTS website for updates and newly published TECHOPs.

- TECHOP (G-01 - Rev1 - Jan21) TECHOP PHILOSOPHY
- TECHOP (G-02 - Rev1 - Jan21) POWER PLANT COMMON CAUSE FAILURES
- TECHOP (G-03 - Rev1 - Jan21) CONTINUOUS TRIALS FOR DP MODUS
- TECHOP (G-04 - Rev1 - Jan21) CONDUCTING EFFECTIVE AND COMPREHENSIVE DP INCIDENT INVESTIGATIONS
- TECHOP (D-01 - Rev1 - Jan21) ADDRESSING C³EI² TO ELIMINATE SINGLE POINT FAILURES
- TECHOP (D-02 - Rev1 - Jan21) FMEA TESTING
- TECHOP (D-03 - Rev1 - Jan21) BLACKOUT RECOVERY
- TECHOP (D-04 - Rev1 - Jan21) EVALUATION OF PROTECTION SYSTEMS
- TECHOP (D-05 - Rev1 - Jan21) FMEA GAP ANALYSIS
- TECHOP (D-06 - Rev1 - Jan21) DGNSS POSITION REFERENCE SENSORS
- TECHOP (D-07 - Rev1 - Jan21) PROVING FAULT RIDE-THROUGH CAPABILITY OF DP VESSELS WITH HV POWER PLANT
- TECHOP (D-08 - Rev1 - Jan21) SOFTWARE TESTING
- TECHOP (D-09 - Rev1 - Jan21) PRS AND DPCS HANDLING OF PRS
- TECHOP (D-10 - Rev1 - Jan21) DNV RP D102 FMEA GAP ANALYSIS
- TECHOP (D-11 - Rev1 - Jan21) REDUNDANCY CONCEPT PHILOSOPHY DOCUMENT (*update in progress*)
- TECHOP (O-01 - Rev1 - Jan21) DP OPERATIONS MANUAL
- TECHOP (O-02 - Rev1 - Jan21) ANNUAL DP TRIALS AND GAP ANALYSIS
- TECHOP (O-03 - Rev1 - Jan21) DEFINING CRITICAL OPERATIONS REQUIRING SELECTION OF CRITICAL ACTIVITY MODE
- TECHOP (P-01 - Rev1 - Jan21) PART 1 – COMPETENCY FOR DP PROFESSIONALS - DP SMEs - DP FMEA PRACTITIONERS
- TECHOP (P-01 - Rev1 - Jan21) PART 2 – APP1 - COMPETENCY FOR DP PROFESSIONALS - DP SMEs - DP FMEA PRACTITIONERS
- TECHOP (P-01 - Rev1 - Jan21) PART 3 – APP2 - COMPETENCY FOR DP PROFESSIONALS - DP SMES - DP FMEA PRACTITIONERS
- TECHOP (P-01 - Rev1 - Jan21) ADDENDUM - COMPETENCY FOR DP PROFESSIONALS - DP SMEs - DP FMEA PRACTITIONERS

- IMCA M04/04 “Methods of Establishing the Safety and Reliability of Dynamic Positioning Systems”.
- IMCA M166 Rev 1 “Guidance on Failure Modes and Effects Analysis (FMEA)”

Note FMEAs are a requirement to obtain DP Class 2 and 3 notation. Whilst not stipulated as a class requirement for DP 1 vessels owners/ operators are encouraged to subject their DP 1 vessels to the DP FMEA process.

Note Particular attention should be paid in the DP FMEA to the interfaces between the DP system and other systems that have the potential to affect the DP system, such as where the vessel is fitted with an Emergency Shut Down (ESD) system, pipe tensioner system or fire monitor system.

3.3.11 Key DP personnel, including the vessel Master, DPOs, Engineers and Electricians should have a detailed knowledge of the DP FMEA and should use the information provided to be fully informed about the capabilities and limitations of the vessel’s DP system.

3.3.12 The results from a DP FMEA, in particular issues related to the vessel’s worst case failure and significant single point failures, should be used in the formulation of operational, emergency response and planning decisions.

Note: DP Vessel owners may consider applying the principles of analysis given DNVGL’s RP D102 – Recommended Practice for FMEA of Redundant Systems – in preparing DP FMEAs for their vessels and MODUs.

3.4 DP FMEA GUIDANCE NOTES

3.4.1 These Guidance Notes on DP FMEAs are intentionally brief. They give a concise overview of the underpinning philosophy, analytical processes and the technical content of a DP FMEA. Relevant IMCA guidance, referred to in this section, should be consulted to gain a more detailed understanding.

3.4.2 A DP FMEA should encompass the following:

- identify worst case failure design intent (WCFDI) and worse case failure (WCF),
- identify the equipment or subsystem, modes of operation and the equipment,
- Identify all potential failure modes and their causes, including cross connections and external interfaces,
- identify the significant single point failures,
- identify potential hidden failures,
- identify potential configuration errors,
- evaluate the effects on the system of each failure mode,
- Identify measures for eliminating or reducing the risks associated with each failure mode,
- identify trials and testing necessary to prove the conclusions,
- be updated after any major modifications and proving trials have been conducted,
- be subject to review and update as necessary, once every five years. The review should take account of new equipment and hardware/ software updates, new developments in analysis and new knowledge acquired in the intervening period,
- take account of action items from DP FMEA Proving Trials, Annual DP Trials, audits and incidents which have been or, are in the process of being, closed out,

- take account of non DP systems/ auxiliary/ external systems that have interfaces with, and potential impact on DP and station keeping. These systems should be subjected to the FMEA and Proving Trials approach for software, hardware and interfaces thus ensuring the integrity of the DP system and proper integration with DP,
- take account of common mode failures that are otherwise liable to be overlooked, such as the effects of hydrocarbon gas on engine control and safety systems, which can cause diesel engines to accelerate out of control resulting in catastrophic mechanical failure and potential for black out,
- be presented as a narrative analysis of DP related systems and subsystems covering the above points (i.e. redundancy concept, hidden failures, configuration errors, etc.) and be supported by sketches and drawings,
- for DP Class 3 vessels, should consider the effects of fire and flood, not only from a compartment analysis perspective but also, where significant, at the subsystem level, e.g. the effects of fire and flood on ESD control lines and push buttons.

Note Where the redundancy concept relies on inter-switching mechanisms, the reliability and effectiveness of these mechanisms should be proven and fully documented in the DP FMEA.

Note The DP FMEA should contain an analysis of the DP control system I/Os to verify that it is consistent with the redundancy concept and should be proved at DP FMEA Proving Trials.

Note The DP FMEA for a DP MODU should address the ESD function, in particular the various issues relating to the status of post activation battery power supplies (UPS). Appropriate guidance is given in section 6.6 of IMCA M196, "Guidance on the Design, Selection, Installation and Use of UPS onboard Vessels".

Note The findings from a DP FMEA and Proving Trials should be categorised into A, B or C. Categories should be clearly defined. Appropriate definitions are as follows:

Category A The failure effects exceed the worst case failure design intent or some aspect of the design is non-compliant with the ...Insert Classification Society... rules for notation ...Insert DP Notation... Improvement is recommended.

Category B The failure effects equal the worst case failure design intent. The design complies with the ...Insert Classification Society... rules for notation Insert DP notation... but should be reviewed to determine whether a cost effective improvement can be made.

Category C Observations, comments and suggestions associated with DP safety and reliability, which ...Insert Owner... may consider.

3.4.3 A FMECA is an extension of an FMEA that adds a risk assessment of each failure mode to determine its criticality. Criticality is derived from an assessment of the probability that a particular failure will occur combined with the severity of the failure if it does occur.

3.4.4 A DP FMECA should encompass all of the listed points in DP FMEA above and, in addition, include the following steps:

- determine the severity of each failure mode,
- determine the probability of occurrence of each failure mode (using qualitative or reliable MTBF data),
- determine and rank the criticality of the identified failure modes from highest to lowest,
- determine a strategy for dealing with the ranked criticalities so that remedial measures are directed appropriately in accordance with the criticality ranking.

3.4.5 The Criticality Analysis should be presented in tabulated form making use of risk matrices that comply with recognised international standards such as those given in IMCA M166 or IEC 60812.

Note: The closing out of action items should be well documented and auditable.

3.4.6 The following IMCA Guidelines address the above considerations in various levels of detail; M166, M04/04 and Annex.

3.4.7 A DP FMEA should be referred to at the following times:

- conducting task based DP operational risk assessments, where key personnel involved should have detailed knowledge of the DP FMEA,
- determining the DP vessel's Mode of Operation (CAM/TAM)), e.g. where the unavailability of equipment may reduce the vessel's DP station keeping ability,
- determining the DP vessel's Well Specific Operating Guidelines (WSOG), e.g. where equipment performance approaches or exceeds predetermined limits,
- determining the vessel's Task Appropriate Mode, when applicable and warranted by the specific DP operations,
- developing planned maintenance schedules, taking account of the impact of taking systems or equipment out of service,
- developing the vessel's DP Operations and Emergency Response manuals and procedures,
- developing DP trials programs and checklists, ensuring that the single point failures identified in the DP FMEA are covered in the trials and checklists.

Note to Owners In the case of newbuilds, if DP FMEAs are within the shipyard's scope of supply, owners are recommended to ensure that there are contractually binding agreements for the FMEA to meet specifications set out in IMCA Guidelines, M166. M219, M04/04 and Annex and preferably be carried out by an independent third party DP FMEA practitioner.

Cautionary Note DP FMEAs that are solely focused on attaining class notation and class approval may not always meet guidance standards contained in those IMCA Guidelines.

3.5 DP CAPABILITY PLOTS

3.5.1 DP Capability Plots should be calculated for the vessel. Guidance is provided on DP Capability Plots in IMCA M140 Rev 1, "Specification for DP Capability Plots".

3.5.2 DP Capability Plots are theoretical calculations that provide information about expected performance during DP station keeping operations while exposed to external forces. The calculations are based on finding the equilibrium of the steady state forces and moments of the vessel and provide estimates of the vessel's static holding capabilities.

3.5.3 These theoretical plots are calculated from detailed information of the vessel's hull and superstructure form and available thruster power. The calculations should use environmental data (seastate, wind and current) appropriate to the area in which the DP vessel is to operate.

3.5.4 The plots should also take account of changes in the wind or drag coefficients caused by execution of industrial functions, such as pipe tension, heavy lifting drag, hawser tension, etc.

3.5.5 These plots should show the limiting wind speed 360 degree envelopes for the scenarios below, where each point on the envelope represents the wind speed at which it is calculated that the vessel will be unable to maintain position in DP.

3.5.6 DP Capability Plots should include the following scenarios at current speeds of 0kts, 1kt and 2kts, or at other current speeds that are representative of the location in which the DP vessel is to operate:

- Fully intact power generation and thrusters.
- Loss of most effective thruster(s).
- Following the worst case failure.

Note The DP Capability Plots should be provided in a format that is intuitive to the user on board (e.g. Polar Plot).

Note DP Capability Plots do not indicate the accuracy of the vessel's station keeping nor the excursions of the vessel. That is the function of DP Footprint Plots.

Note DP vessel owners are encouraged to consider the advantages of conducting Dynamic Time-Domain Simulations which provide a more realistic representation of the vessel's expected performance than is achievable using the static equilibrium method.

3.6 DP CAPABILITY PLOTS GUIDANCE NOTES

3.6.1 DP Capability Plots that do not cover Worst Case Failure are incomplete. DP Capability Plots that do not take into account thruster interaction, (thruster-thruster, thruster-hull), thruster degradation and thruster barred zones are incomplete.

3.6.2 Owners/ operators should note that it is important to provide a detailed scope of work to whoever is to generate the DP Capability Plots for the vessel. Experience has shown that those who generate the DP Capability Plots, such as the DP system manufacturers, may not include the Worst Case Failure, unless specifically instructed to do so. This is particularly relevant where the DP Capability Plots are included in the shipyard's scope of supply for newbuilds.

3.6.3 DP Capability Plots may have to be recalculated from time to time during the lifetime of a DP vessel. For example, the installation of new equipment, such as a crane or an accommodation module on deck will alter the vessel's outline, which, in turn, will alter the wind effect on the vessel. In these circumstances the DP Capability Plots should be recalculated to take account of the changes.

3.6.4 DP Capability Plots may also have to be recalculated for thruster configurations where, due to unforeseen faults or failures or, due to essential maintenance requirements, one or more thrusters are no longer available. Where not already covered by existing calculations the revised DP Capability Plots should cover the following cases for the new thruster condition, i.e. the new fully intact condition, the new loss of most effective thruster(s) and the new worst case failure condition.

3.6.5 DP Capability Plots should be readily available to the DPOs at the DP control console.

3.6.6 DPOs should consult DP Capability Plots as a matter of course whilst the vessel is conducting DP operations.

3.6.7 DPOs should be fully familiar with the limits given in the DP Capability Plots for the fully intact thruster configuration, for loss of most effective thruster and for worst case failure.

- 3.6.8 DPOs should be careful when estimating the current force acting on the vessel and relating it to the DP Capability Plots. DPOs should be aware that the current force generated by the DP control system is the residual external force acting on the vessel that cannot be measured. When wind speeds are low the attendant vessel, if available, could be used to estimate current by going into drift mode.
- 3.6.9 DP Capability Plots should be used by DPOs and other key DP personnel as a reference in the planning phases when determining the vessel's environmental operational limits for the WSOG. Where the DP Capability Plots show an undue level of heading limitations this may restrict the vessel's operating range. This is not uncommon on vessels, such as DP tankers, that have good fore and aft thrust capability but limited thwartship capability.
- 3.6.10 It should be remembered that DP Capability Plots are theoretical calculations and that, wherever possible, opportunities should be taken to validate the DP Capability Plots by taking DP Footprint Plots. See below.

3.7 DP FOOTPRINT PLOTS

- 3.7.1 DP Footprint Plots should also be produced on board. DP Footprint Plots are not theoretical. They are actual measurements of the vessel's DP station keeping performance in the actual environmental conditions and thruster configuration at the time the plot was taken. DP Footprint Plots should be taken whenever opportunities arise, such as during standby periods, weather downtime or on arrival at the field. Plots should be taken for the thruster configurations used in the DP Capability Plots, i.e. fully intact, loss of most effective thruster(s) and after worst case failure.
- 3.7.2 Some DP systems have a software application that produces DP Footprint Plots electronically. DPOs can also produce DP Footprint Plots by manual methods using a plotting sheet.
- 3.7.3 DP Footprint Plots serve two main purposes.
- They provide a scatter plot of vessel positions at regular intervals around the required set position (this shows accuracy of station keeping)
 - They also provide comparison points on the limiting wind speed envelope given in the theoretical DP Capability Plots (this shows wind speeds at which it was seen that the vessel was unable to maintain position, thus validating or contradicting the theoretical DP Capability Plots for the various thruster configurations.)
- 3.7.4 DP Footprint Plots serve other purposes, including learning and familiarisation opportunities for DPOs and in providing snapshots of vessel station keeping behaviour for specific locations and activities.
- 3.7.5 Theoretical DP Capability Plots and DP Footprint Plots combine together to enhance knowledge and understanding of the vessel's DP station keeping ability.

Note DP Footprint Plots originated in harsh weather regions, such as in the North Sea. The plots are used to gain a better understanding of the vessel's actual station keeping performance and limitations in intact and, in various degraded thruster configurations, including worst case failure, whilst the vessel is being subjected to real environmental forces.

It is acknowledged that DP Footprint Plots may be of less relevance to DP MODUs.

3.8 DP FOOTPRINT PLOTS GUIDANCE NOTES

3.8.1 Manual DP Footprint Plots are generated in the following manner.

1. Use a proforma plotting sheet, comprising a 360 degree polar plotting diagram, vessel outline with thrusters indicated and space for vessel specific position reference systems and environmental data. Refer to plotting sheets in Appendix A.
2. The vessel should be in auto DP. Record wind, waves and current on the plotting sheet, drawing appropriate vectors.
3. Record thruster configuration on the plotting sheet.
4. Record the rate of turn and speed of moves. It is suggested that the following values are applied, 10deg/min and 0.3m/sec, respectively, to prevent misleading results.
5. Observe position excursions from the intended position by the most appropriate means, plotting the vessel's position regularly, e.g. every 30 seconds.

3.8.2 Appendix A contains two worked examples. Both worked examples are for the same DP semi-submersible drilling rig and in the same environmental conditions. Wind was 45 to 50kts from 225 degrees with a corresponding wave height of 6m. Current was 1 coincident with wind at 1kt.

3.8.3 Example 1 shows a DP Footprint Plot for the rig's fully intact condition with all eight thrusters operational. The plot shows that the vessel was able to maintain position within +/- 2 meters with the wind and sea on the port quarter.

3.8.4 Example 2 shows a DP Footprint Plot for the rig's worst case failure condition with four thrusters operational. The plot shows that the rig was unable to maintain position with the wind and sea on the port quarter.

3.8.5 Example 2 - The known circumstances at the time of taking the DP Footprint Plot, of wind, wave height and thruster configuration, in which the rig failed to maintain position, can be compared against the environmental envelope plotted on the theoretical DP Capability Plot for worst case failure. They should be similar in that the DP Capability Plot should also show that the vessel will be unable to maintain position in conditions where a 45 to 50kt wind is on the port quarter. If there is a significant difference between the two, particularly if the DP Capability Plot shows that the vessel can maintain position in the given condition, then it may be necessary to pull in the limiting wind envelope on the DP Capability Plot to the upper wind speed determined by the DP Footprint Plot for these conditions.

Cautionary Note The DP Footprint Plot positions will contain systematic position reference errors.

3.9 POSITION REFERENCE SYSTEMS AND SENSORS

3.9.1 The DP vessel should be equipped with suitable position reference and sensors in accordance with the vessel's DP class notation and operational requirements. Position reference systems should be selected with due consideration to operational requirements, both with regard to restrictions caused by the manner of deployment and expected performance in working situations.

3.9.2 Position reference systems comprise absolute and relative systems. An absolute system gives vessel geographical position. A relative system gives vessel position in relation to a non-fixed reference. A relative system can be used as an absolute system if installed on a point that is a fixed geographical position. An acoustic absolute system can be used as a relative system if attached to a non-fixed asset.

3.9.3 The following are the most common position reference systems in use.

- | | |
|----------|--------------------------------------------------------------------------------|
| Absolute | DGNSS (DGPS and GLONASS)
Acoustic (USBL, SBL, LBL)
Taut wire
See Note |
| Relative | Artemis
Laser (Fanbeam, CyScan)
Radar (RADius, RadaScan)
DARPS |

Note: Class rules give minimum requirements for the number of position references. Where operational uptime is one of the key success factors the benefit gained by consciously exceeding the minimum requirements are to be evaluated. Other benefits of exceeding minimum requirements include greater redundancy and improved station keeping performance.

Caution Additional position reference systems should be based on different principles. It is generally not recommended to use multiple (>2) satellite based systems in conjunction with other position reference systems as this may result in skewed weighting in favour of multiple satellite systems.

Note It could be debated that Taut Wire and Acoustic Position reference systems are relative position reference systems. For purposes of this document, absolute indicates that both the Taut Wire and Acoustic position reference sensors are independent of other¹³ fixed or floating offshore structures.

3.10 POSITION REFERENCE SYSTEMS AND SENSORS GUIDANCE NOTES

3.10.1 Operational guidance on position reference systems and sensors is given in the table below.

Cautionary Note: The water depth limits given in the table below for acoustic positioning systems are for guidance only.

3.10.2 Evidence from operational experience has shown that acoustic positioning systems frequently provide acceptable positioning information at deeper water depths than given in the table.

3.10.3 Of particular note evidence from some DP drilling units equipped with SBL/LBL systems has shown the SBL element to be useful up to 2700m, which far exceeds the upper guidance limit of 700m.

¹³ The word “other” refers to own vessel.

Application on DP	Recommended Absolute Position Reference Systems							Recommended Relative Position References Systems if in close proximity to an offshore structure							Sensors	
	GPS	DGNSS (DGPS + GLONASS) (See Note 2 below)	SBL (See Note 1 below)	USBL/SSBL (See Note 1 below)	LBL (See Note 1 below)	Taut Wire (See Note 12 below)	Min Number (See Note 3 below)	Artemis	Laser	Radar	Gangway	DARPS	Min Fixed platform (See Notes 4, 5 & 6 below*)	TLP/SPAR/etc < min movement (See Notes 4, 5 & 6 below*)		TLP/SPAR/etc > min movement (See Notes 4, 5 & 6 below*)
Drilling	If in deep open water	Redundant - one dual frequency	<700m	<700m	>700m	<350m	3	Y	Y	Y	N	N	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
Diving	N	Y	<700m	<700m	>700m	<350m	3	Y	Y	Y	N	N	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
Pipelay	N	Y	N	N	N	N	3	Y	Y	Y	N	N	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
Umbilical Lay	N	Y	N	N	N	N	3	Y	Y	Y	N	N	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
Riser Pull in	N	Y	<700m	<700m	>700m	<350m	3	Y	Y	Y	N	N	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
Lifting	N	Y	<700m	<700m	>700m	<350m	3	Y	Y	Y	N	N	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
Accommodation	N	Y	<700m	<700m	>700m	<350m	3	Y	Y	Y	Y	N	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
Shuttle Offtake	N	Y	N	N	N	N	3	Y	Y	Y	N	Y	3 mixed abs & rel	3 mixed abs & rel	3 relative only	3
ROV Support	N	Y	<700m	<700m	>700m	<350m	2	N	N	N	N	N	*	*	*See Note 8 below	2
Floating Production Unit	N	Y	<700m	<700m	>700m	<350m	3	N	N	N	N	N	NA	NA	NA	3
Well Stim	N unless open water	Y	<700m	<700m	>700m	<350m	2	Y	Y	Y	Y	Y	2	*	*	2

Application on DP	Recommended Absolute Position Reference Systems							Recommended Relative Position References Systems if in close proximity to an offshore structure							Sensors	
	GPS	DGNSS (DGPS + GLONASS) (See Note 2 below)	SBL (See Note 1 below)	USBL/SSBL (See Note 1 below)	LBL (See Note 1 below)	Taut Wire (See Note 12 below)	Min Number (See Note 3 below)	Artemis	Laser	Radar	Gangway	DARPS	Min Fixed platform (See Notes 4, 5 & 6 below*)	TLP/SPAR/etc < min movement (See Notes 4, 5 & 6 below*)		TLP/SPAR/etc > min movement (See Notes 4, 5 & 6 below*)
OSV Snatch Lifts	N	Y	<700m	<700m	>700m	<350m	2	Y	Y	Y	N	N	1	2 mixed abs and rel	2	2
OSV HAZMAT Transfer no quick disconnect	N	Y	<700m	<700m	>700m	<350m	3	Y	Y	Y	Y	N	2	3 mixed abs & rel	3 relative only	3
OSV HAZMAT Transfer with quick disconnect	N	Y	<700m	<700m	>700m	<350m	2	Y	Y	Y	Y	N	2	*	*	3
OSV with shaft gens and single stern thruster	N	Y	<700m	<700m	>700m	<350m	2	Y	Y	Y	Y	Y	3	*	*	3
Wind Turbine installation	N	Y	NA	NA	NA	NA	2	N	N	N	N	N	NA	NA	NA	2
Standby Vessels	Y	Y	<700m	<700m	>700m	<m	1	N	N	N	N	N	NA	NA	NA	1 or <

Note 1 (Acoustics) – The acoustic LUSBL system is not included in the above table since it is a combination of USBL and LBL in one system, where the USBL is typically used to calibrate the LBL system. Although standalone USBL systems are not the norm on DP drilling MODUs it is not unknown for SBL and USBL systems to be operated as independent units in addition to LBL.

3.10.4 The abbreviations, USBL and SSBL, are referred to in the above table. Although the abbreviations differ, they both refer to the same acoustic application although supplied by different vendors.

3.10.5 It is recommended that, wherever possible, multiple acoustic systems are completely separated and independent in all respects. For instance, this would require the use of separate and independent hull transceivers.

3.10.6 Owners/ operators should consider the advantages of acoustic positioning systems that have an inertial navigation input, such as the Kongsberg HAIN (Hydro Acoustic Inertial Navigation) system or Sonardyne's AAINS (Acoustically Aided Inertial Navigation System) both of which can,

- overcome the update rate limitations of speed of sound in water,
- overcome the limitations on satellite based position reference systems brought upon by poor satellite geometry.

3.10.7 DPOs should be aware of potential conflicts arising from operations taking place onboard their vessel and in close proximity to them. This is particularly relevant to acoustic systems being used by survey teams, BOP acoustic communications systems and acoustic frequencies used by nearby logistics or project/ construction vessels.

Note 2 (Satellite Systems) – Satellite based systems that use a combination of signals from DGPS and GLONASS satellites provide enhanced redundancy over systems that use only a single satellite source.

3.10.8 It is recommended that, wherever possible, multiple satellite based systems are completely separated and independent in all respects. For instance, this would require the use of different masts for the satellite antennae, separate cable routing, different vendors and software. Where there is diversity of vendors and software it is recommended that the acceptance/ rejection logic is verified against the DP system manufacturer's specifications. There have been incidents in the past where diversity of vendors and software has resulted in loss of position due to the acceptance of erroneous values within the software.

3.10.9 Care should be taken at all times when using satellite based systems close to platforms. Guidance is given in IMCA M141, "Guidelines on the Use of DGPS as a Position Reference in DP Control Systems", which highlights potential problems when within 150m of a platform, such as the masking of GPS signals, masking of differential signals, radio interference and multipath. Good DGPS close to structures should be considered as a bonus. In these locations DGPS should not be considered as the primary position reference system.

3.10.10 Where multiple DGPS systems are being used, consideration should be given to set each system with a different elevation mask. This is so that any jump in position that may occur when a satellite comes into view will hit one DGPS before the next and will give the DPO some time to take action.

3.10.11 Owners/ operators should consider the advantages of hybrid GNSS/ IMU positioning systems, such as the Kongsberg Seatex 4D system, where an inertial input is applied to the satellite based system's position calculation. This enhancement can fill the "holes" in positioning information in extraordinary and difficult conditions that otherwise might invalidate the satellite based positioning information, such as during times of scintillation and satellite ageing.

Note 3 (Absolute Systems) - Where three absolute systems are used it is recommended that they are based on two different principles. Only where it is impractical to use systems based on different principles should all three be of the same type. This is of particular significance where DGPS is concerned where the satellite constellation provides a source for a common mode failure.

Note 4 (DP at non fixed Assets, e.g. FPSOs/ TLPs/ Spars) – When carrying out DP activities in close proximity to or in conjunction with floating facilities it is strongly recommended that redundant relative position reference systems are used. In these situations, a mix of absolute and relative position reference systems for station keeping is to be used only after validating that movement of the floating structure, if any, does not impact station keeping. The DPOs must be extremely vigilant when using a mix of absolute and relative position references and must be fully aware of the potential danger of diverging positioning information from both types of system.

3.10.12 The minimum movement referred to in the table above refers to the actual measured movement of floating facility, e.g. FPSO/TLP/SPAR. To measure this movement the DP vessel should use an absolute position reference system, such as DGPS, as the sole source for positioning information and use the relative positioning system, such as RADius, RADASCAN or Fanbeam, sited on the floating facility to measure the fluctuations in its movement.

3.10.13 It should also be noted that there are non-fixed offshore facilities, such as TLPs and Spars where an acoustic system, although normally considered as an absolute system, can be used as a relative system. This can be accomplished by installing the transponder/ beacon onto the submerged part of the TLP or Spar at an appropriate depth. Some TLPs and Spars are fitted with suitable subsea brackets or cradles for transponders/ beacons.

Note 5 (Absolute and Relative Systems) - When using DGPS/ GLONASS in a mix of absolute and relative position reference systems, in particular where there are two satellite based systems in a mix of three, users should bear in mind the possibility of the offshore structure blocking the satellite signals and the consequences for station keeping.

Note 6 Wherever practical and feasible it is recommended that redundancy requirements are met by diversity of suppliers, e.g. satellite based position reference systems from different manufacturers and differential signals from different sources. This applies equally to sensors such as gyro compasses, VRUs and wind sensors.

Note 7 (Sensors) - Given the impact on heading/ position keeping it is recommended that vessels with an equivalent DP 2 class notation are provided with three gyro compasses, irrespective of the requirements of the applicable Classification Society DP rules. It should be noted that some Classification Societies, including ABS and DNV already require three gyro compasses for a DP class 2 notation.

3.10.14 Gyro compasses are normally fitted with a correction facility which inputs the vessel's latitude and speed. The effects of incorrect latitude or, more importantly, speed could result in a significant error in output heading. It is therefore important to ensure that the latitude and speed corrections are applied. Some systems use automatic input from GPS for these corrections. This is not recommended since there are a number of system errors that can result in undesired heading changes. It is therefore recommended to use manual input of latitude and speed.

- 3.10.15 Wind sensors are known to have suffered common mode failures, such as icing in higher latitudes, lightning, heavy rain and birds. All types of wind sensor are vulnerable, including ultrasonic types. Where ultrasonic type wind sensors are fitted, the consequences for station keeping of common mode failures, that affect these ultrasonic sensors, may be prevented by fitting mechanical wind sensors.
- 3.10.16 DP vessels are frequently fitted with sensor systems, other than heading, motion and wind, which have a potential to affect the DP system and station keeping should there be an erroneous or invalid input from them. These include draft sensors and pipelay tension sensors, where an erroneous or invalid input could result in extreme values and distortion of external forces and result in large position excursion (drive off) from the desired set point position. There should be means of preventing erroneous values from being accepted by DP. An often practiced procedure which should prevent the above problems is to input these values manually and not to rely on the automatic input function, if fitted. There should also be means of ensuring that erroneous values are prevented from being input manually.
- Note 8 Where it is anticipated that due to operational requirements the DP vessel will require to be positioned in close proximity to the non-fixed facility and where the potential for shadowing of DGPS exists, then redundancy in relative position reference sensors should be considered.
- Note 9 Where, as is normal, multiple position references are in use by DP, the DPOs should monitor the weightings closely so as to ensure that no one system or set of systems is ‘hogging’ the weighting. DPOs should recognise the potential dangers of using multiple satellite based systems (>2) in the suite of position reference systems and that this could result in skewed ‘weighting’ in favour of satellite systems at the expense of other position references. It is recommended that no more than two satellite based position reference systems be used to provide position solution as inputs into DP. Where additional position reference systems are available but not selected for use, they should, if possible, be put into monitor mode to allow for monitoring and, if necessary, for quick selection into the DP control system.
- Note 10 New or retrofitted position references are sometimes interfaced into DP through inputs designed for other position references because the DP control system has not been designed to accept them. Examples of this are pseudo Artemis or pseudo acoustics. This practice is not recommended unless accompanied by a detailed risk analysis and the residual risk, if any, is deemed acceptable. Wherever possible the displays for such position reference systems should be located in close proximity to the DP control location. This allows for quick identification and evaluation of erroneous positions.
- Note 11 The practice of connecting survey and DP is not recommended. Where it is unavoidable, galvanic isolation between the systems is to be provided. DPOs should have ultimate control over the input. All necessary precautions should be taken to ensure that the vessel’s station keeping is not affected and should be addressed in the FMEA.
- Note 12 (Taut wires) – Care should be exercised when lowering or repositioning taut wire weights that divers and ROVs are alerted and are a safe distance from the seabed position. Taut wire weights should also be placed clear of pipelines, manifolds or other subsea assets. These subsea assets should be positively identified prior to positioning taut wire weights, e.g. by the ROV. Care should also be taken that the taut wires are not fouled by other subsea lines or obstructions.

- 3.10.17 It is possible for thruster wash to interact with a taut wire, acting as a strong current and causing position instability. The thruster wash could be from own vessel or from another vessel close by. DPOs should be aware of the potential for this to occur.
- 3.10.18 DPOs should be alert to the potential for taut wire weights to “skip” along the seabed and provide inaccurate positioning information. This can be avoided by ensuring that the tension control is properly calibrated and operating within specified parameters and that the angle of wire inclination is kept as near to vertical as is possible and should not normally exceed 10 degrees.
- 3.10.19 DPOs should also be aware of the potential for taut wire systems to become a “perfect” reference. This can have different causes, including the taut wire touching the side of own vessel or otherwise being restricted in its movement, or by a faulty gimbal sensor. Most DP systems will detect this fault. DPOs should ensure that the warning and alarm limits are properly set and operational.
- 3.10.20 The wires in use in modern taut wire systems are generally 5mm or 6mm in diameter. Weights are in the region of 400kg to 500kg. Taut wires are quite highly stressed for marine wire ropes and are liable to breakage, particularly at points of weakness, such as continuous wear at the spot on the main sheave, continuous wear at any guide blocks and kinks or damage caused by poor spooling or where the wire is attached to the weight. The potential for wire breakage is reduced by regular inspection of the taut wire system and by slipping and cutting (cropping) the taut wire on a regular basis.
- 3.10.21 Taut wire systems are known to suffer inaccuracies at water depths over 350m, especially in high current areas. This should be taken into consideration when planning DP operations.
- Note 13 It is important that software, parameters and values used by position reference systems are compatible with the software and acceptance criteria used by the DP control system and that this is verified by analysis and testing.
- 3.10.22 Attention is drawn to IMO MSC/Circ 645 where three MRU/VRUs are stipulated when vessel positioning is fully dependent on correct MRU/VRU signals.
- Note 14 Lightning strikes on DP vessels can cause severe and catastrophic harm to personnel and equipment. This is particularly relevant to DP MODUs and drillships operating in areas susceptible to high levels of lightning activity. Owners should assess the risks and, where found necessary, install lightning protection and surge protection equipment onboard their DP vessels.

3.11 REGIONAL RECOMMENDATIONS FOR DP DRILLING UNITS

- 3.11.1 Owners/ operators of DP drilling units should consider adopting the following standards for hydroacoustic and satellite systems for deepwater DP drilling operations. The adoption of these standards should enable the DP drilling unit to operate anywhere in the world.
- 3.11.2 Hydroacoustic Systems
- A minimum of two independent acoustic systems each one with internal redundancy as to transponders/ beacons and transducers/ hydrophones capable of operating in maximum specified water depths with such a configuration that allows a minimum of 0.5% of water depth in 95% of measurements. Each acoustic system should have redundancy in the input of sensors (gyros and VRUs) and each transducer/ hydrophone should have redundancy in electrical supply. Whilst making this recommendation it is recognised that there are many DP drilling units already in operation that are not equipped with dual independent acoustic systems. In such cases owners are encouraged to consider the benefits of upgrading to dual independent systems.

- Acoustic systems operating in a master/ slave relationship or hot standby should be avoided. They should simultaneously supply the DP controllers as totally independent position reference systems. The designation of weight or deselection of a faulty position reference system should be performed automatically by the DP controllers without DPO intervention.

Note In deepwater applications where weighting adjustments by DPO may be required, detailed procedures are to be provided.

- The DP drilling unit should have a number of transponders/ beacons sufficient to constitute submarine arrays capable of operating in the maximum water depth, including redundancy on the bottom for the configuration of each operational mode and the back ups on the surface. In addition, DP drilling units should be provided with reliable deployment and retrieval systems such as the use of ROVs for deployment and retrieval and may also include acoustic release systems.
- Where not fitted owners are encouraged to consider the benefits of providing, as an additional function, the primary actuation of the acoustic system driving the back up of BOP (with redundancy) via hull transducers. The BOP specific portable acoustic unit should be used only in exceptional circumstances, such as failure of the primary system or abandonment of the platform.

Cautionary Note where acoustic BOP systems are required, there is potential for interference by the use of equipment provided by multiple acoustic vendors.

- Consideration should be given to using USBL as a top down means of calibrating LBL systems. This will optimise calibration times as well as improving accuracy.

3.11.3 Satellite Based Systems

- Two independent satellite positioning systems should be in operation, each with minimum accuracy of three meters. The primary receivers should have GPS dual frequency (L1/L2) in addition to one GLONASS receiver. Each system should have double redundancy in the differential signal reception system as follows; two different satellite systems, for example, Inmarsat and Spot Beam and two different radio systems with distinct frequencies and redundant transmitter stations with range covering the whole operational scenario of the Unit (i.e. DP drillship or DP semi), for example, IALA MF and UHF.
- Note Availability of the local radio system Infrastructure varies by region.
- Each satellite positioning system should have redundancy in the input of sensors (gyros and VRUs).
- Antennae (both primary GPS and differential) should be situated in different places on the Unit spaced apart in order to guarantee redundancy and minimize shadow sectors.
- The satellite systems should provide the DP controllers with positioning reference information simultaneously and independently.

3.12 RECOMMENDED DP CONTROL MODES FOR DP ACTIVITIES

- 3.12.1 In addition to basic DP modes such as Auto Position, DP Joystick, Auto Heading and related combinations the DP vessel should be equipped with suitable DP modes and features with due consideration to operational requirements, both with regard to restrictions caused by the activity and performance criteria required to execute the activity safely and successfully.

3.12.2 The following selected DP control modes are relevant to specific DP activities.

Target Follow (aka Follow Target)

Enables the DP vessel to follow a moving target and is used, for example, to follow an ROV along a pipeline.

Auto Track Enables the DP vessel to follow a specified track described by waypoints and is used, for example, for survey operations, cable or pipeline deployment.

Heavy Lift Takes account of the effects of the load transfer on the mass of the vessel and the additional lateral force, normally by reducing gain and relaxing the DP controller.

External Force Compensation

Where the measured external force acting on the vessel, which is separate from the environment, is included in the DP calculation and treated as a force feed forward. This mode is used to account for pipe tensions in a pipe layer and hawser tension in a shuttle tanker.

Fire Monitor Compensation

Used to compensate for the varying forces exerted on vessel from the fire monitors.

Anchor Assist

Provides thruster assistance when the vessel is moored within an anchor pattern. Sometimes referred to as Thruster Assisted Mooring (TAM), which is not be confused with Task Appropriate Mode.

Weathervane

Enables the DP vessel to rotate with the wind, current and waves around a fixed or moving point called the terminal point. Neither the heading nor the position of the DP vessel is fixed. The heading of the vessel is controlled to point towards the terminal point. The position of the vessel is controlled to follow a circle, called the setpoint circle, around the terminal point. This mode is appropriate for connected shuttle tanker/ FPSO operations.

Caution It is not uncommon for the term “weathervane” to be used to denote “minimum thrust”, i.e. where the DP control system allows the vessel’s heading to rotate to minimize external forces acting on the vessel and thruster requirements. These terms should not be confused.

3.13 DP CONTROL MODES FOR DP ACTIVITIES GUIDANCE NOTES

3.13.1 The following table contains a list of many of the recommended DP control modes and applicable DP activities.

Table 3-2 Recommended DP Control Modes

Activity on DP	Weather	DP Control Mode			
		External Force Comp	Target Follow	Weather Vane (See Note 2 below)	Heavy Lift Mode
Drilling	N	N	N	N	N
Diving	N	N	N	N	N

Activity on DP	Weather	DP Control Mode			
		External Force Comp	Target Follow	Weather Vane (See Note 2 below)	Heavy Lift Mode
Pipelay	N	Y	N	N	N
Umbilical Lay	N	N	N	N	N
Riser Pull in (See Note 3)	N	Y	Y	N	N
Lifting	N	N	N	N	Y
Accommodation	N	N	Y	N	N
Shuttle Offtake	N	N	Y	Y	N
ROV Support	N	N	Y	N	N
Floating Production Unit	NA	N	N	Y	N
Well Stim	<i>if class 1</i>	N	N	N	N
OSV Snatch Lifts	<i>if class 1</i>	N	N	N	N
OSV HAZMAT Transfer no quick disconnect	Y	N	N	N	N
OSV HAZMAT Transfer with quick disconnect	N	N	N	N	N
OSV with shaft gens and single stern thruster	<i>Needs to head into weather</i>	N	N	N	N
Standby Vessels	<i>Y if class 1</i>	N	N	N	N

- Note 1 The term “down weather” means that the vessel is on that side of the offshore structure where the environmental forces, acting on their own, would move the vessel away from the structure. An alternative term is that the vessel is on the “force off” side of the structure.
- Note 2 The term “weathervane” has a specific meaning in the DP shuttle tanker industry.
- Note 3 The vessel specific DP Operations Manual should contain sufficient detail of these operating modes and features.
- Note 4 The DPOs are to familiarize themselves with operational constraints/ requirements of these modes and features.
- Note 5 A detailed and documented risk assessment should be carried out when it is planned to perform any of the above activities without the recommended DP control mode.
- Note 6 Where DP vessels, such as DP MODUs carrying out subsea construction activities, are engaged in activities outside their normal scope they should do so using the recommended DP control mode. This may mean that the mode has to be installed in the DP control system.

3.14 TRIALS AND CHECKLISTS

- 3.14.1 A range of trials and checklists is to be provided for each DP vessel and implemented as a verification that the vessel's DP system complies with and, is operated in accordance with, applicable standards and guidelines. This verification process should confirm the failure modes and their effects on the systems and equipment analysed in the DP FMEA document (to include the Worst Case Failure) and the vessel's station keeping ability following its Worst Case Failure. Owners/ operators should refer to the following list of trials and checklists when developing an appropriate regime for their own DP vessels. The list below is a typical list for a DP dive support vessel.
- 3.14.2 DP FMEA Proving Trials (also refer to section 4.2 of this guidance document) A series of tests used to prove expected effects of failure modes found in the FMEA desktop analysis. These tests should also include the testing of interfaces between different vendor systems and equipment. These tests should be conducted immediately following launching and full commissioning of a new build vessel and thereafter following modifications, additions, upgrades or repairs.
- 3.14.3 Endurance Trials:- (new build/ system modifications class requirement): To prove the operation of the DP system under load conditions for at least 4 hours without significant alarms of the DP system.
- 3.14.4 Annual DP Trials:- A series of tests of fault and failure conditions relevant to the DP System. The tests should be designed to prove system redundancy, as defined in the DP FMEA, system performance and equipment functionality, to validate repairs and preventive maintenance, and test the operation of protection and detection devices and responses so as to demonstrate that the vessel's DP system remains fit for purpose. Annual DP Trials should be performed at a specific time once a year within 3 months of the anniversary date of the vessel's initial DP FMEA Proving Trials. Annual DP Trials also provide the opportunities for training of the vessel's crew and enhancement of their knowledge of failure modes and their effects.
- 3.14.5 Annual DP Trials are frequently used by clients in auditing and in the acceptance of vessels prior to going on hire.
- 3.14.6 Detailed industry guidance on Annual DP Trials is given in IMCA M190, "Guidance for Developing and Conducting Annual DP Trials for DP Vessels", in IMCA M191, "Guidelines for Annual DP Trials for DP Mobile Offshore Drilling Units", in IMCA M212 "Example of an Annual DP Trials Report", in M225 "Example Redundancy Concept and Annual DP Trials for a DP Class 3 Construction Vessel" and in in MTS TECHOP (O-02 - Rev1 - Jan21) ANNUAL DP TRIALS AND GAP ANALYSIS.
- Note Experience has shown that, owing to heavy operational demands, DP drilling units are not usually able to meet the above criteria for conducting Annual DP Trials at a specific time once a year. This has been recognized by the industry with publication of specific guidance relating to the conduct of Annual DP Trials for DP MODUs. This is given in IMCA M191, "Guidelines for Annual DP Trials for DP Mobile Offshore Drilling Units". The guidance sets out a regime of annual testing that is conducted on an incremental or continuous basis throughout the year as opportunities arise but needs to be completed within a twelve month period.
- 3.14.7 DP Mobilization Trials: A series of tests to be carried out at the start of a contract, subject to client requirements, to demonstrate redundancy and functional limitations of the DP system.
- 3.14.8 DP Field Arrival Trials: A series of checks and tests that confirm satisfactory performance of the DP system and verify the set up mode of operation and DP functions.

- 3.14.9 DP Location Set Up Checklist: A series of checks to demonstrate that the vessel is properly set up for the location, in particular the satisfactory performance of the position reference systems.
- 3.14.10 Pre-Dive Checklist: A series of checks performed prior to commencing diving operations. Main and back up communication tests should be included in this process.
- 3.14.11 ECR Checklists: A series of checks and tests that verify that the vessel's set up and configuration of systems and equipment meet the requirements of Critical Activity Mode (CAM) or Task Appropriate Mode (TAM).
- 3.14.12 500m Checks: A series of checks and tests performed before entering the 500m zone of an asset in which set up mode and functions are verified and confirmed. Approval is then obtained to operate in close proximity to the asset. Main and back up communication tests should be included in this process.
- 3.14.13 Watch Status/ 6 Hour Checklist: A series of checks and tests performed by the DPOs to verify and confirm the setup of the DP system prior to taking over the DP watch.
- 3.14.14 Post DP Incident Trials: Tests performed to ensure that the corrective/ repair measures taken following a DP incident have properly addressed the causes of the incident and that the vessel's DP system is in a safe and operable condition.
- 3.14.15 Post DP Modification Trials: A series of checks and tests that are used to determine the effects of modifications and/ or additions on the DP system and the vessel's subsequent station keeping performance.

Note The nomenclature used for the trials and checklists listed above is based on the guideline document, IMCA M112, "Guidelines for Auditing Vessels with DP Systems". It is recognized that these trials and checklists could be given other titles.

3.15 ANNUAL DP TRIALS FOR MODUS GUIDANCE NOTES

- 3.15.1 The following guidelines apply to the development and the conduct of Annual DP Trials for a DP MODU in accordance with guidance contained in IMCA M191. M191 guidance describes a regime of annual testing that is conducted on an incremental or continuous basis throughout the year as opportunities arise but needs to be completed within a twelve month period. M191 also recognises the contribution that planned maintenance systems can play in verifying the status and performance of certain DP equipment throughout the year.

M191 gives the purpose of Annual DP Trials as follows:

"..... to improve the DP system safety and performance by testing faults and failure conditions important to DP safety to prove the ability of the vessel to keep position after single point failures associated with the IMO equipment class and to verify the FMEA requirements. When faults identified during the year on similar DP MODUs are determined to be feasible on the vessel then additional tests should be incorporated in the trials program."

Using the above quotation as the background, owners/ operators should use the vessel specific DP FMEA and Proving Trials as the principal source for developing the Annual DP Trials program.

DP Mobilization Trials

These trials should be carried out by the vessel's crew as part of the mobilizing program prior to the start of a new project. The tests carried out at these trials are less than are carried out at Annual DP Trials but more than at DP Field Arrival Checks. The tests should confirm the vessel's redundancy concept and station keeping performance after worst case failure. They should also provide assurance of the integrity of the vessel's DP system and the vessel's operational limitations.

DP Field Arrival Checks

These checks should be carried out on arrival at the field. The purpose of these checks is to ensure satisfactory operation of the DP system and should include a full functional check of the operation of all thrusters and power generating equipment and systems, auto DP and all control modes. The checks should also ensure that the DP system is set up properly.

DP Field Move Checks

These checks are particularly relevant to DP MODUs and drillships where moves are of short duration and take place inside the field. These checks are less intensive than Field Arrival checks since the rig remains on DP with BOP suspended. The checks ensure the DP system remains fit for purpose.

DP Location Set Up Checklist

These checks should confirm that the vessel is properly set up for the working location and that the performance of the position reference systems is satisfactory for that location. These checks should take account of any limitations of the position reference systems for that location. These checks should be repeated for each change of location.

ECR Checklists

These checks should be carried out by the ER staff and reported to the DPOs prior to start of operations and at fixed periods during DP operations. These checks should be developed from the vessel's DP FMEA and should confirm that the vessel's systems and equipment are set up and configured for the appropriate operating mode. It is the responsibility of engine room watch personnel to advise the DPOs, at any time, of any abnormalities in relevant systems or equipment that may affect DP operations.

500m Checks

500m checks are not normally applicable to DP MODUs. All OSVs and other vessels should undertake 500m checks. Only vessels engaged in support activities to remain within the 500m zone of the DP MODU. The 500m zone is not to be used as a standby location unless required to support a specific activity.

Watch Status/ 6 Hour Checklist

The purpose of these checks is to record the status of the DP system and configuration. The checks should verify that the vessel's station keeping performance at the working location is satisfactory and, in particular, that the position reference systems are properly set up and operating satisfactorily. No testing is carried out for these checks. DPOs should complete the checklist prior to taking over the watch, not during the first few minutes of the watch.

Post Modification/ Upgrade DP Trials

It is essential to ensure that any modification, change or upgrade to the DP system is fully tested and that the vessel's redundancy concept has not been affected. Testing should follow on from a detailed FMEA type analysis of the change which should be fully documented.

The following example shows the inherent dangers of failing to take proper account of change. In this example the installation of a more up to date and faster OS computer resulted in the new computer re-booting too early and failing to “ride through” the brief power interruption that resulted from the activation of a changeover relay. This resulted in the temporary loss of that operator station.

3.16 DP OPERATIONS MANUALS

- 3.16.1 A vessel specific DP Operations Manual should be prepared for each DP vessel.
- 3.16.2 The requirement for a manual has its origins in IMO MSC/Circ 645 (1994) “Guidelines for Vessels with Dynamic Positioning Systems”.
- 3.16.3 The IMO Guidelines require a series of checklists, test procedures and DP operating instructions to be incorporated into one manual.
- 3.16.4 Each Classification Society has its own specific requirements for a DP Operations Manual, each with different requirements for content.
- 3.16.5 The high level recommendations set out below address areas that are not necessarily required by class. They are based on current industry practices and guidance contained in MTS DP “TECHOP (O-01 - Rev1 - Jan21) DP OPERATIONS MANUAL”.
- 3.16.6 The manual should contain sufficiently detailed instruction and guidance to enable the vessel to be operated safely in DP and safely execute its intended activities. This will include a clear statement on the DP philosophy for the vessel, guidance on the vessel’s redundancy concept and worst case failure, configurations for CAM and TAM, the organisation, responsibilities and roles of key DP personnel, training and competency, watchkeeping and manning, vessel technical data and layout, vessel DP capabilities, operating limits, operating modes, the planning and preparation of DP operations, DP operating procedures, simultaneous operations, emergency procedures, DP incident handling and alert systems and vessel specific trials and checklists that apply uniquely to the vessel.
- 3.16.7 The manual should also specifically address operational interfaces between different vendor systems and equipment to ensure that they are configured and operated properly. This should include interfaces between systems and equipment that are not part of the DP system but which may affect the DP system, such as Emergency Disconnect Systems (EDS) on MODUs, tensioner systems on Pipelay vessels, etc.
- 3.16.8 The vessel specific manual may also contain generic content, such as company policies, procedures and standing orders.
- 3.16.9 The manual should represent the way the vessel is operated in DP. For complicated power systems and/ or thruster configurations, it may be useful provide the operator with a thruster and generator operating strategy (TAGOS) to assist in the decision on what generators and thrusters to use for different circumstances and different equipment availabilities.
- 3.16.10 Guidance on the contents of vessel specific DP Operations Manuals is provided in the following:
- MTS DP TECHOP (O-01 - Rev1 - Jan21) DP OPERATIONS MANUAL.
 - IMCA guidelines, IMCA M103 Rev 2 “Guidelines for the Design and Operation of Dynamically Positioned Vessels”
 - Classification Society DP rules.

3.17 DP OPERATIONS MANUALS GUIDANCE NOTES

- 3.17.1 The provision and development of the manual is the responsibility of the DP vessel owner or manager and should be incorporated in the company's SMS and, where relevant, developed and managed in accordance with Requirement 7 of the ISM Code, which states, as follows:

“The Company should establish procedures for the preparation of plans and instructions, including checklists as appropriate, for key shipboard operations concerning the safety of the ship and the prevention of pollution. The various tasks involved should be defined and assigned to qualified personnel.”

- 3.17.2 The manual should be a standalone document in hard copy. Owners/ operators, at their discretion, may provide this in an electronic format.
- 3.17.3 The manual should be readily accessible to all relevant DP personnel, including the master, DPOs, engineers and electricians. At least one controlled copy including any updates and, where necessary, appendices should be kept on the DP navigating bridge.
- 3.17.4 All relevant DP personnel should be given sufficient opportunity to familiarise themselves fully with the document and should be fully conversant with the sections of the manual that relate to their duties and responsibilities.
- 3.17.5 The manual should address operating issues relating to equipment and systems that are interfaced to the DP system. This will include ESD systems installed on DP MODUs, where the consequences of an automatic shutdown triggered by an ESD may result in well control problems. The potential for this adverse situation should be assessed and appropriate preventative measures put in place. Due consideration should be given to initiating disconnect sequence preceding an ESD resulting in a black out. Detailed procedures are to be developed for operating ESD. Procedures should highlight criteria for initiation and consequences.
- 3.17.6 Owners/ operators may wish to refer to the following guidance when developing the vessel/ rig specific DP operations manual:

- Section 1 Management of DP Operations (company/ rig specific).
 Company/ rig standing operational policies.
 Basic principles of DP, functional overview of a DP control system.
 Vessel/ rig specific overview of DP system (vessel overview document).
 Vessel/ rig specific DP philosophy, CAM/TAM , WSOG, open/ closed bus-tie configurations, worst case failure, environmental envelopes, vessel/ rig DP station keeping capabilities.
 Related DP guidance and reference documents.
- Section 2 DP System Description and Operation (vessel/ rig specific).
 Power generation, distribution, electrical systems, thrusters and propulsion (thruster and generator operating strategy, TAGOS).
 Power management, auxiliary systems, fire and flood.
 DP control system and automation, DP computers and operator stations and networks, including, operating modes.
 Position reference systems and sensors; DGNSS/ Hydroacoustic/ riser angle monitoring and management, taut wires, gyros, VRUs, wind sensors draft sensors, current sensors, etc.
 Communications systems, internal and external, routine and emergency.

Disconnect systems; auto/ manual emergency shutdown systems (ESD), emergency disconnect system (EDS [disconnect sequence]), other emergency and alert systems. (The failure modes of these systems and the potential effects on the vessel's station keeping ability should be addressed in the DP FMEA).

Section 3

DP Operations Procedures

Procedure for planning DP operations, including environmental criteria, use of DP capability analysis and DP footprints, DP system set up, power and propulsion set up, required levels of redundancy, position reference system planning, integration with well planning, simultaneous operations, risk assessment.

Development of WSOG (well specific operating guidelines), requiring input from riser analysis and drift off study, proven blackout recovery times and EDS (disconnect sequence) times and determination of red and yellow watch circles. Development of well specific criteria for normal, advisory, degraded and emergency conditions, WSOG communications and response procedures. emergency DP procedures, including drive off, drift off, force off, blowout/ shallow gas, fire and/ or explosion, loss of well control, severe weather, loss of DP position references, loss of redundancy, black out, collision, squalls, etc.

Position reference system deployment, operation and recovery, including hydrophones, acoustic arrays, battery procedures, DGPS set up and differential corrections, other PRS procedures.

Normal DP marine operations, including voyage, transit and field arrival checklists, Annual DP Trials, mobilization trials, field arrival checklists, location set up checklists, watch handover checklists, well planning and pre-departure checklists, ESD/ EDS trials (where appropriate), 500m safety zone operations, optimum position and heading, position and heading changes, standby time, data logging, offset and turn testing, ROV operations, helicopter operations, operations in strong currents, adverse and heavy weather procedures, special operations.

DP drilling interfaces, including running/ pulling BOP, landing BOP, stabbing in, disconnecting BOP, drifting, running and pulling riser, emergency disconnect systems, riser management, flex joint angles, slip joint and tensioner stroke, stress limitations and wellhead bending moments, vortex induced vibrations, simultaneous operations.

Communications, including routine internal communications, external locations, emergency procedures, testing, alert systems, typical communications protocols and messages.

DP incident definition, investigation, reporting, close out and record keeping.

Section 4

Organisation and Responsibility

DP organisation, including onboard organisation, key DP personnel, DP technical and operational support onshore and offshore, manning levels.

Duties and responsibilities of key personnel involved in DP operations, examples, master, DPOs, chief engineer, engineers, electrical officers, ETOs, rig superintendent, toolpusher, driller, etc.

Onboard watch routines, watchkeeping duties, DP desk procedures, DP handover procedures, DP log keeping and documentation, including weather log, beacon log, DP standing orders, bridge and engine room, drillers shack,

DP training, familiarisation and competency assessment, including onboard programs and experience levels, skills development, emergency training, drills and exercises.

DP reporting and record keeping, including daily reporting, monthly DP status report, tests and trials reporting, DP incidents and equipment failure reports, vendor reports, DP correspondence, reporting matrix, etc.

Operator Intervention Appendix

3.18 ACTIVITY OPERATIONAL PLANNING

3.18.1 In recognizing that exposure to risks manifests itself during vessel operations it is recommended that activities performed by DP vessels including those related to the vessel's industrial mission, should be subject to planning and preparation. In planning and preparing for the activities the following should be considered and, where appropriate, documented.

3.18.2 HAZOP (Hazard and Operability Study) and HEMP (Hazards and Effects Management Process) are useful tools here and may be used as the platform for identifying, assessing and dealing with risks associated with complex activities and for determining when to use CAM and TAM configurations.

- Configuration for the Critical Activity Mode of Operation (CAM) or, where appropriate, the Task Appropriate Mode (TAM).
- Preparation of the Activity Specific Operating Guidelines (ASOG), including onboard discussion with all relevant stakeholders as part of the pre-project execution/ activity and industrial mission.
- Discussion to be included in pre-project execution readiness checklist.
- Capabilities of the vessel, both intact and residual capability, following Worst Case Failure (WCF).
- Limitations imposed by water depth.
- Consequences of a loss of position and/ or heading.
- Limitations imposed upon operations by residual capability.
- SIMOPS and marine vessel interaction and consequences arising from change of status (Green to Blue, Yellow or Red).
- The activity being performed and the necessary time to terminate to bring vessel to a safe position upon the onset of failure.
- Initiating "Positioning Standby"

3.18.3 Activities should include day to day operations, any specific operation relevant to the design of the vessel, as well as any unique operations the vessel is called upon to perform.

3.18.4 Appropriate measures should be in place to clearly identify critical tasks/ operational phases of the activity and to ensure that the vessel is set up in the agreed to Mode (CAM or TAM). Criteria for operations undertaken as CAM should be within post WCF capability. Where a decision has been made to operate in a TAM a separate ASOG covering TAM should be produced.

Note The ASOG should be developed by extracting all the relevant information from detailed technical review of the vessel's DP FMEA, operational manuals and project specific procedures. The ASOG should be validated on board.

On a DP MODU, ASOGs are known as WSOGs. Some owners refer to it as WSOC (Well Specific Operating Criteria) or WSOP (Well Specific Operating Plan).

- 3.18.5 Guidance on Activity Operational Planning is given in IMCA M220 “Guidance on Activity Operational Planning”, IMCA M103 Rev 2 “Guidance on the Design and Operation of Dynamically Positioned Vessels” and in MTS DP TECHOP (O-03 - Rev1 - Jan21) DEFINING CRITICAL OPERATIONS REQUIRING SELECTION OF CRITICAL ACTIVITY MODE.

3.19 POSITIONING STANDBY GUIDANCE NOTES

- 3.19.1 Positioning standby is a condition that is triggered during the execution of the Industrial Mission when warranted. Positioning standby is initiated to bring all station keeping critical elements (Equipment, People, Processes) to a higher state of readiness, for a defined period, with the objective of preventing a loss of position by
- Ensuring that all needed equipment is available and or running where necessary.
 - People are in position to respond to an event and prevent escalation.
- 3.19.2 Positioning Standby may initiate the following actions:
- A change in configuration from TAM to CAM.
 - Cessation of non-critical activities, including suspension of routine IRM during the period when positioning standby is in effect (personnel in right places).
- 3.19.3 Examples of positioning standby are:
- Non shearables through stack.
 - Increase in Time to Terminate (TTT).
 - Casing landing/cementing operations.
 - Well test operations.
 - Deteriorating weather
 - Station Keeping Equipment issues.
 - Difficulties being experienced in Industrial mission (challenging reservoir conditions).
 - Making significant changes to the DP configuration such as putting large consumers, for example a thruster or engine, or closing or opening a bus tie breaker.

3.20 CRITICAL ACTIVITY MODE (CAM)

- 3.20.1 Any DP vessel/ rig, including DP Class 2 and 3, can have the redundancy concept defeated if its systems and equipment are not configured or operated in the correct way. CAM is the DP system configuration, including power generation and distribution, propulsion and position reference systems, that provides the highest level of station keeping integrity so that the DP system, as a whole is as fault tolerant and fault resistant as it can be.
- 3.20.2 Critical activities are those that have potential for escalation that could lead to unacceptable consequences such as personnel injury, major equipment damage or damage to the environment. Typically, such industrial operations have any or all of the following characteristics:
- Low tolerance for unintended position changes
 - Long termination time
 - Vessel operations within 500 metre zone of another asset.
- 3.20.3 CAM is generally presented in a tabulated format. The CAM table also sets out the operator actions should the required configuration fail to be met.

3.20.4 CAM sets out the required equipment configurations and operational standards necessary for the vessel to meet its maximum level of redundancy, functionality and operation so that no single failure will exceed worst case failure. Every DP vessel/ rig has a unique CAM configuration which must be determined from a detailed understanding of the vessel's DP FMEA and its operational characteristics. The CAM configuration should be the default operational mode for a DP vessel/ rig, when conducting activities deemed or identified as critical.

3.20.5 A detailed review of the DP FMEA is done with a view to identify CAM. It is suggested that the results of this review are summarised in a vessel overview document. This overview document in conjunction with CAM, WSOG and TAGOS could be a useful tool to new onboard personnel involved in operations. The WSOG should be accompanied by a single line drawing (SLD) of the power generation, distribution and propulsion systems.

3.21 TASK APPROPRIATE MODE (TAM)

3.21.1 TAM is a defined DP system configuration which strives to offer station keeping integrity and fault tolerance but not to the same extent as CAM. TAM is a risk based mode.

3.21.2 TAM is the configuration that the vessel's DP system may be set up and operated in, accepting that a failure could result in effects exceeding the worst case failure such as blackout or loss of position. This is a choice that is consciously made.

3.21.3 TAM may be appropriate in situations where it is determined that the risks associated with a loss of position are low and will not result in damage to people, environment or equipment. The conditions under which a DP MODU may operate in TAM are defined and are usually associated with a short time to terminate. Activities where TAM is considered should be supported by documented risk assessment.

3.21.4 TAM also offers practical benefits that arise from reductions in the use of DP equipment and DP machinery.

Note Task Appropriate mode in this context is not to be confused with Thruster Assisted Mooring

3.21.5 TAM may be considered for MODUs when appropriate for non-critical activities. Risk assessments used to validate use of TAM should take into account:

- Fault tolerance/ fault resistance and fault ride through capability of Station Keeping critical elements.
- The benefits of power plant stability (usually the reason why TAM is considered) versus the potential for a complete loss of the power plant and the consequences.

3.21.6 The configuration for CAM and TAM on diesel electric vessels will be dependent on the particular features of the vessel's electrical power plant and protection systems. For some, TAM may mean operating with closed bus and CAM may require open bus. For others, CAM may be a closed bus configuration. This may occur on vessels designed to operate with closed bus where open bus is not a safe operating mode. On those vessels, where CAM is a closed bus configuration the DP FMEA and Proving Trials should show that no single failure, including over/under excitation, over/under frequency, will cause loss of position.

Example 1 A DP MODU may operate TAM during times when Time to Terminate is short, and in CAM when Time to Terminate is long.

Example 2 A DP pipelay vessel may operate in TAM when more than 500m from a surface or mission critical subsea asset, and in CAM when inside 500m.

Example 3 A DP logistics vessel may operate in TAM when down wind and down current within the 500 metre zone of an asset and/or with a short time to terminate. CAM may be applicable when working up wind and up current within 500m of an asset and/or when time to terminate is long.

3.22 WELL SPECIFIC OPERATING GUIDELINES (WSOG)

- 3.22.1 The WSOG differs from the CAM and TAM in that it relates specifically to a known location and activity and, in the case of a DP drilling vessel/ rig, to a specific well operation. The WSOG performs the same function as Activity Specific Operating Guidelines (ASOG), which relate to non-drilling activities. The WSOG differs from the CAM and TAM in that the WSOG sets the operational, environmental and equipment performance limits for the DP vessel/ rig in relation to the specific well that it is operating on, whereas the CAM and TAM may not be well or location specific. A WSOG should be developed for every well and location.
- 3.22.2 Two central components in the WSOG are, proven knowledge of black out recovery time and, knowledge of the disconnect time. Reference should also be made to the drift off study and the riser analysis for the intended location. The drift off study will provide, among other things, vessel/ rig movement from the wellhead measured in time after loss of all propulsion power in a number of environmental conditions, including one year return and ten year return conditions. Other conditions may be considered, such as where strong currents are likely to be experienced. The riser analysis will, among other things, provide the point of disconnect (POD). This point is the first point reached where mechanical damage to the riser is considered to occur and will depend on water depth, mud weight, riser tension, stroke of telescopic joint, etc.
- 3.22.3 The one year return condition is typically used as the environmental criteria in the WSOG. Where the environment is below that condition and a black out occurs, it may not be necessary to go straight to a RED. A YELLOW may be appropriate. This will give the blackout recovery sequence an opportunity to bring the thrusters back on line. However, in these circumstances, if the RED watch circle is reached before restart of the thrusters, then an EDS (disconnect sequence) is initiated.
- 3.22.4 The WSOG should consider colinearity, i.e. where current and wind are from the same direction.
- 3.22.5 In some cases, where the one year return environmental conditions produces a very tight RED watch circle or, where a RED watch circle is not possible even after offsetting the vessel/ rig into the environment, then consideration could be given to reducing the environment criteria to 99% or even 95% of the one year return values accepting the potential consequences of increased non-productive time.
- Summary A DP drilling vessel/ rig should always be set up in accordance with its predetermined CAM or when determined to be appropriate, in TAM. CAM is the default mode for Critical Activities. Additionally, a decision to implement positioning standby or, the result of risk assessments could initiate a change in mode from TAM to CAM as a preventive measure or as a mitigation. WSOG should always be developed and implemented by a DP drilling vessel/ rig for every well operation that it carries out.
- Note The vessel owns the CAM/TAM and WSOG document and the process that is used to develop it from inception through to implementation.
- 3.22.6 Refer to APPENDIX D for an example of a CAM and WSOG for a DP drilling rig.

3.22.7 The CAM/TAM is presented in a tabulated format and shows two conditions (GREEN – NORMAL) and (BLUE – ADVISORY)¹⁴ for each item, as follows.

Table 3-3 Critical Activity Mode (CAM or TAM) – Outline

CRITICAL ACTIVITY MODE (CAM or TAM) – OUTLINE		
	GREEN	BLUE
Definition	Normal operations – all systems and equipment fully operational, DP verification processes completed and DP set up confirmed.	Advisory status – where any of the GREEN conditions are not met.
Response	For DP operations to commence and continue the conditions in the GREEN column must be met.	Conduct risk assessment to determine whether to continue, change position or cease operations.

3.22.8 The CAM/TAM goes beyond equipment set up. It also defines operational standards. Typical items contained in the CAM/TAM will include the following:

- Power plant set up, including whether operating open or closed bus.
- Diesel generators, including confirmation of 100% output in DP.
- Thrusters, including confirmation of 100% output in DP.
- Power management, including configuration, confirmation that auto stop is off, black start enabled.
- Uninterruptible power supplies (UPS), including confirmation of power supply, functional testing, no cross connections.
- Manual controls and independent joystick, including confirmation of readiness and testing.
- DP control system, including consequence analysis, mode availability and selection.
- Position reference systems, including availability, testing and selection, absolute and relative systems, placement of targets for DP OSVs.
- Set speed of rotation and speed of moves, suggest 10deg/min and 0.3m/sec, respectively.
- Sensors, including availability, testing and selection.
- Fuel systems, including confirm redundancy, tank levels, standby starts, isolations, crossovers.
- Sea water cooling, including confirm redundancy, standby starts, isolations, crossovers.
- Fresh water cooling, including confirm redundancy, standby starts, isolations, crossovers.
- Compressed air, including confirm redundancy, safest compressor operating mode.
- DP and ER manning, including watchkeeping rotas, qualifications and competency of watchkeepers.
- Trials and checklists.
- ESD status.

¹⁴ The choice of colours, GREEN and BLUE, are based on industry norms. However, some owners/ operators have chosen different colour combinations.

3.22.9 The WSOG is presented in a tabulated format and shows four conditions (GREEN – NORMAL), (BLUE – ADVISORY), (YELLOW – REDUCED) and (RED – EMERGENCY)¹⁵, as follows:

Table 3-4 Well Specific Operating Guidelines - Outline

WELL SPECIFIC OPERATING GUIDELINES - OUTLINE				
	GREEN	BLUE	YELLOW	RED
Definition	Normal operations – all systems fully functional and operating within acceptable performance limits.	Advisory status – approaching performance limits or reportable alarm status. Operations may continue whilst risks are being assessed. A failure has occurred that does not affect DP redundancy.	Actionable status - Pre-defined performance limits reached, component or system failure resulting in loss of redundancy. The vessel/ rig maintains position although the vessel has lost its redundancy.	Emergency status – pre-defined operational or performance limits exceeded, component or system failure resulting in loss of control or position.

3.22.10 A WSOG for a DP drilling rig will typically cover the following items:

- Maximum watch circles radius for one year return conditions.
- Colinearity conditions of wind and current (including one year return conditions).
- Weather forecast and environmental conditions, including wind speed limits, current speed limits, wave height limits.
- Rig positioning performance (weather related), including position and heading excursions.
- Drilling offset from wellhead position.
- Drape hose limitations.
- Long turn.
- Riser limitations (UFJ and LFJ).
- Drive off, drift off scenarios.
- Diesel generators, including minimum number required for the activity, performance limits and failures (TAGOS).
- Diesel generator loads (TAGOS).
- Thrusters, minimum number required for the activity, performance limits and failures (TAGOS).
- Thruster loads (TAGOS).
- Phase back conditions (including thruster phase back, drilling phase back and DP control system power limiting).
- Battery and UPS systems.
- PMS and VMS status and operation.
- Auxiliary systems, including fuel, SW and FW cooling, air – performance limits and failures.

¹⁵ The choice of colours, GREEN, BLUE, YELLOW and RED are based on industry norms. However, some owners/ operators have chosen different colour combinations.

- Uninterruptible power supplies (UPS), including operation, charger output and supply status, failures.
- DP control system, including operation and performance of DP controllers and OS, failures:
 - DP control system displays, including mimics, performance and failures.
 - DP networks, including operation and redundancy, failures.
 - Position reference systems, including number of enabled systems and performance, failures.
 - Sensors, including number of enabled systems, performance and criticality to activity, failures.
 - Critical communications, including onboard systems, performance and failures.
 - Non-essential DP systems, including ventilation and a/c – performance and failures.
 - Fire, flood, visibility, collision, including threat to safety of the DP operation.
 - Simultaneous operations, including communications with assets.

Note 1 Drift off curves and time and distance to point of disconnect (POD) are extracted from the rig’s riser drift-off analysis for a variety of conditions, including one year return conditions, ten year winter storm return conditions and where appropriate, specific return conditions such as ten year loop current conditions.

Note 2 Where the one year return environmental condition produces a tight RED watch circle or even where a RED watch circle may not be possible even if the rig is offset upstream, the benchmark environment could be reduced to a 99% or even 95% of one year return conditions. In situations where the benchmark environment has been reduced consideration should be given to enhancing weather and seastate monitoring such as by a wave rider buoy (shallow water applications).

3.23 COMMUNICATIONS

- 3.23.1 The vessel should be equipped with the appropriate primary and secondary equipment needed to communicate between all parties (stakeholders) whilst carrying out the intended task.
- 3.23.2 Effective internal and external communications is a key tool to manage risk.
- 3.23.3 Communications in this context include voice, visual (lights/ displays) and audible means (alarms). Means of communication are not limited to the above but include integrated IT systems using wireless network technology that combine communications with other features, including AIS and DGNSS.
- 3.23.4 Operational specific visual and voice communications should ensure that the pertinent information flows between the key operating points as well as to and from assets and/ or other vessels that might be affected by the operation being carried out.
- 3.23.5 These operating points may be onboard the vessel as well as on other facilities involved with the activity. Communication protocols are to be set up to provide pertinent information regarding intent, current status of planned as well as unexpected events during the execution of the activity.
- 3.23.6 Continuity of communications during foreseeable emergency situations should be taken into account.

- 3.23.7 Communications should be taken into account when detailing the roles and responsibilities of key personnel during the planning stages for the intended task, ensuring that a common working language and terminology is used at all times.
- 3.23.8 Guidance on communications is provided in IMCA M103 Rev 2 (Guidance on the Design and Operation of Dynamically Positioned Vessels), MSF M182 Rev 2 “International Guidelines for the Safe Operation of Dynamically Positioned Offshore Supply Vessels” and IMCA M205 “Guidance on Operational Communications”.
- Note The importance of communication to be emphasized by incorporating into the ASOG.

3.24 COMMUNICATIONS GUIDANCE NOTES

- 3.24.1 There should be redundant voice communications systems to all key locations on board the DPO vessel. At least one of the systems should be hands free. The DPO should have a view or CCTV coverage of all important operational areas onboard as well as of important points of interest external to the vessel.
- 3.24.2 Communications and alarm systems should be protected against power supply failure. Battery/ UPS back up power supplies are recommended.
- 3.24.3 Some modern communications and alarm systems rely solely on software activated alarms through the network. This sole dependency is not recommended. Manual activation of alarms should never be overlooked in design or in operation.
- 3.24.4 Communications and alarm systems for all DP related equipment and systems and other equipment and systems not directly related to DP, but which will have an effect on DP, should be located close to the DP control station. This should include fire zone alarms systems.
- 3.24.5 Simultaneous operations (SIMOPS) depend on effective communications between all vessels and units involved in the operation. It is important that change of status between vessels and units engaged in SIMOPs is communicated speedily and reliably. It should be noted that developments in sensor and communications technologies are underway to relay, among other things, change of vessel or unit CAM/TAM or WSOG status. With these systems any change of status from GREEN to BLUE, YELLOW or RED will be instantaneously relayed to all vessels and units engaged in SIMOPs. These technologies are expected to deliver and aid in the management of complex SIMOPS.

3.25 DP PLANNED MAINTENANCE

- 3.25.1 DP vessels should have a structured planned maintenance system that specifically addresses maintenance of the vessel’s DP system, equipment and support systems.
- 3.25.2 Planned maintenance should address all equipment that has an impact on the vessel’s station keeping capabilities. This should include indirect components such as generator circuit breakers, bus tie breakers, etc. Maintenance should include regular cleaning, calibration, and testing of equipment as outlined in manufacturer’s recommendations and industry guidelines.
- 3.25.3 Records of planned and unplanned maintenance should be kept in an auditable format, either hard copy or appropriate electronic format. These records should include vendor service records as well as maintenance performed by vessel personnel. These records should be kept on board for the period specified by the owner/ operator.

3.25.4 A minimum number of required critical DP spares should be maintained on board. The critical spare inventory should be monitored via a formal inventory program that is closely linked to the planned maintenance system. This should assist in getting back to normal operating condition after equipment failure or DP incident.

Note The client's due diligence process is usually the main driver in the critical path to return to normal operating condition. Typically, this also involves vendor support as well as the client's DP consultant.

Note Maintenance on DP related equipment whilst conducting DP operations should be controlled by a documented permit to work system and should always take into consideration the potential alteration of failure modes and increased criticality of failure consequences on DP capabilities and/ or redundancy.

3.25.5 Further guidance is given in IMCA M109, Rev 2 "A Guide to DP-Related Documentation for DP Vessels".

Guidance Notes

3.25.6 It should be recognised that DP MODUs may from time to time require that certain items of equipment are temporarily taken out of service for the purposes of essential planned maintenance. Where thrusters and/ or generators are temporarily taken out of service this is likely to have an impact on the rig's DP capability and its worst case failure.

3.25.7 In preparation for these occasions, it is recommended that a thruster and generator operating strategy (TAGOS) is developed to take account of the impact on DP capability and/ or worst case failure. If the impact on DP capability and/ or worst case failure is significant, it is suggested that additional DP capability plots correlated to the TAGOS be provided on the vessel.

3.25.8 It is also recommended that a thorough barrier management system is implemented prior to removing a critical piece of equipment for preventive maintenance. Effective barrier management requires there to be two tried and tested barriers.

3.25.9 It is recognised that deferring scheduled planned maintenance due to work activities increases the potential for failures. Vessel operational teams are encouraged to incorporate planned maintenance as a guideword in HIRAs. (Hazard Identification and Risk Assessments)

Note The potential for common mode failures increases where same vendor equipment of same type and age are installed and in operation.

Example Simultaneous failure of three wind sensors of similar type and hours of service ("aging") accompanied by mechanical stressing resulting from gusts experienced during a hurricane.

3.26 DP INCIDENTS

3.26.1 DP vessels should be provided with and operate appropriate DP incident reporting, investigation and closing out procedures. This should be in accordance with vessel owner or operators' and, if applicable, clients' processes. Documented records should be kept and be capable of auditing.

3.26.2 Where CAM, TAM and WSOG are used as tools to manage DP operations a suggested approach is that, apart from the exceptions in the notes below, any reactive change of DP status from GREEN to YELLOW or RED should be regarded as a DP incident, and should be reported, recorded and investigated.

Note A change of status triggered by prearranged agreement between the Master, and senior onboard decision makers, allowing the vessel to exceed environmental limits should not be regarded as a DP incident.

Note An operator initiated change of status as a result of a conscious decision based on risk analysis of the circumstances where the trigger points have not been reached should not be regarded as a DP incident.

3.26.3 It is recommended that reactive YELLOW and RED DP incidents are investigated as soon as practicable after the DP incident and, where relevant, trials are carried out as part of the investigation process.

3.26.4 The purpose of the investigation and the trials should be:

- to assist in identifying the root causes of the incident, including immediate and underlying causes.
- to evaluate all contributing factors and identify preventive measures.
- to verify and validate that measures to address the root cause are effective.
- to validate that effective measures have not introduced any additional potential to cause failures (both hidden and apparent).

3.26.5 In the event of the occurrence of a DP incident relating to the vessel's configuration as described in the DP FMEA and other documents, it is suggested that the FMEA provider is involved in the incident investigation. This will facilitate lessons learnt to be implemented into the DP FMEA and proving trials program.

3.26.6 Owners/ operators of DP vessels are encouraged to share lessons learned from DP incidents with the wider DP community. DP systems and equipment vendors are also encouraged to do likewise and to share information on unexpected faults, features and failures that are identified in operation. IMCA's station keeping incident reporting scheme provides a suitable channel for reporting and disseminating relevant information throughout the DP sector. Additionally, the MTS DP Committee has created the Lessons from Incidents (LFI) portal on their website which provides owners and operators of DP vessels with a facility to report DP incidents. Both schemes are voluntary and anonymous.

3.26.7 Separately, further detailed guidance on DP incident investigation is given in MTS DP TECHOP (G-04 - Rev1 - Jan21) CONDUCTING EFFECTIVE AND COMPREHENSIVE DP INCIDENT INVESTIGATIONS.

Guidance Notes

3.26.8 The IMCA station keeping incident reporting scheme has been in place for many years and annual reports are published each year which summarise each reported incident as well as providing an overview of all the incidents for the year. These annual reports are available to IMCA members and non-members alike.

3.26.9 The MTS DP Committee LFI portal contains summaries of DP incidents reported to the MTS. The portal also gives access to a more detailed description and analysis of reported DP incidents and puts forward lessons learned and recommendations to prevent recurrence.

3.26.10 Owners/ operators are recommended to make these reports available to key DP personnel onboard their vessels so that they can learn from the experience of others.

- 3.26.11 The IMCA station keeping incident reporting scheme and the MTS scheme and all other repositories of DP incidents need the support of the whole DP community to be an effective learning, sharing and risk mitigating tool. It is acknowledged that there could be a reluctance to participate in sharing of incidents for fear of unwanted disclosure of company identification as the source of the DP incident. Industry bodies who provide repositories for incident reporting are encouraged to provide anonymity and positively communicate this to the DP community. Owners/ operators are encouraged to draw upon learnings from incidents experienced and avoid recurrence.
- 3.26.12 Vessel operational teams are encouraged to systematically evaluate potential for incidents on their own units based on published analysed information. Where additional technical support is required to aid this systematic analysis, it should be sought.

3.27 REPORTING AND RECORD KEEPING

- 3.27.1 Owners or operators of DP vessels should have an effective reporting and record keeping system.
- 3.27.2 There should be a clear line of reporting DP related items onboard the DP vessel and between each department and this should involve key DP personnel. There should also be a clear line of reporting between the DP vessel and the company's shoreside management. DP related records should be maintained onboard and, where appropriate, at the company's premises.
- 3.27.3 The documents and records contained in table A, Section 3.2 should be accessible to key DP personnel and to other interested parties.
- 3.27.4 DP vessels, on occasion, carry out activities which may be unique to project requirements. Records of these activities including pertinent information from Hazards and Risk Identification (HIRAs) should be made and kept onboard for future reference, both for training and familiarisation processes as well as for reference in case of similar project requirements in the future.

Guidance Notes

- 3.27.5 The following records should be kept and made accessible to vessel crew and to other interested parties.
- DP FMEA & FMEA Proving Trials reports.
 - Annual DP Trials.
 - DP checklists for bridge and engine room.
 - DP incident investigations & close out reports (see Note 1 below).
 - DP system faults, repairs, modifications and upgrades (see Note 2 below).
 - Vessel specific familiarisation and training for short service employees involved in DP operations and ongoing training and development programs for experienced DP personnel.
 - Operational logs & DP alarm print outs.
 - DP data logging records.
 - DP system equipment vendor reports.
 - DP Footprint Plots.
 - Vessel overview documents, CAM/TAM and WSOGs, TAGOS.

DP vessels, on occasion, carry out activities which may be unique to project requirements.

Effective record keeping of such activities has the following benefits:

- assists in identifying best practices.
- demonstrates the vessel's performance.
- facilitates knowledge capture and transfer.
- assists in identifying or justifying equipment improvements.

Guidance on reporting and record keeping is provided in M109, M163.

Note 1 Owners/ operators should recognise the benefits that electronic DP data logging systems offer when carrying out DP incident investigations and establishing root cause.

Note 2 Documentation relating to modifications and upgrades should be kept and available for reference. This will include risk analysis of the interfaces and documentation and records of all commissioning and testing.

3.28 COMPETENCE

3.28.1 Definition: Competence is the acquisition of knowledge, skills and abilities at a level of expertise sufficient to be able to perform in an appropriate work setting.

3.28.2 DP vessel owners/ operators should operate a structured competence assurance program that is applied to all key DP personnel with special focus on ensuring vessel and task specific competence.

3.28.3 Vessel specific competency should, as a minimum, be demonstrated in the following areas:

- Operational modes.
- DP FMEA familiarization.
- DP Operations Manual familiarization.
- Project/ activity requirements.
- Contingency plans, modes and drills.

3.28.4 Guidance on competence is provided in IMCA M117 Rev 1 "The Training and Experience of Key DP Personnel". This IMCA guidance document is recognised by the International Maritime Organisation (IMO) and published as IMO MSC Circ 738 "Guidelines for Dynamic Positioning (DP) Operator Training". Relevant guidance is also available in IMCA C 002 Rev 1 "Competence Assurance and Assessment Guidance Document and Competence Training: Marine Division".

3.28.5 Further guidance on competence is given in the MTS DP Committee publication, "Guidance for Professional Development of Personnel Engaged in DP Operations Using the Mapping Delivery Ability Tool" (MDAT).

3.28.6 A number of certification schemes are available to the DP sector which provide training, competence assurance and certification programmes for DPOs and other key DP personnel. These certification schemes are designed to provide owners and operators of DP vessels with a base line of knowledge, understanding and application for DPOs and other key DP personnel. The schemes do not override the duty and responsibilities incumbent on owners and operators of DP vessels to ensure the competence of DPOs and other key DP personnel onboard their vessels.

Nautical Institute

The Nautical Institute (NI) Training and Certification Scheme is the most widespread internationally. The NI scheme was initiated in the early 1980s and set the standard for DPO certification thereafter in particular by placing DPOs certification in two categories; i.e. “unlimited” certificates which are valid for all equipment classes of DP vessel and “limited” certificates which are restricted to DP equipment class 1 and lower. The NI scheme is based on two levels of shore based learning, induction and simulator training complemented by practical onboard experience. The NI scheme has recently been updated with the introduction of assessment and revalidation.

OSVDPA

The OSVDPA (Offshore Service Vessel Dynamic Positioning Authority) provides an alternative DPO certification scheme which has its basis on assessment, simulator training and practical onboard experience. The OSVDPA scheme comprises five phases and leads prospective DPOs through three levels of DPO certification from no certification to Class C to Class B and ultimately the award of a Class A certificate. The scheme includes a revalidation element.

DNVGL SeaSkill

The DNVGL Sea Skill DPO Certification Scheme offers another alternative. It comprises a DP Foundation component which is based on theory and practice, practical onboard experience and a DPO Advanced phase, also based on theory and practice. The DNVGL Scheme offers a partial sea time reduction facility achieved through simulator based training and assessment. DPO certificates are awarded to the candidates on completion of the DPO Advanced phase. The scheme also includes a revalidation element.

Guidance Notes

Key DP personnel include masters, DPOs, engineers, electricians, electronic technicians and anyone involved in the safe position keeping capabilities of the vessel and includes those involved in the deployment of PRSs. Owners/ operators are responsible for their competency and are encouraged to develop their own competency verification processes for all key DP personnel.

IMCA M117 provides the DP sector with detailed guidance on the training and experience of key DP personnel. M117 has been adopted by the IMO and issued as IMO MSC/Circ 738 (1996). A reference to M117 is also made in the MODU Code.

M117 provides guidance on formal training courses for DPOs and other key DP personnel, including watchkeeping marine engineers and electronic maintenance staff. M117 recognises the formal training and certification scheme for DPOs administered by the Nautical Institute. The current version of IMCA M117 predates the emergence of other DPO certification schemes.

Brief outlines of all three schemes, Nautical Institute, OSVDPA and DNVGL SeaSkill schemes are given in Part 1 of this theme, see above.

DPO certification is only one part of the competency assurance process for DPOs. Such certification is not to be construed as validation of competency.

Owners/ operators are recommended to refer to further formal training programs described in M117, comprising the following main features for electrical and engineering officers, where appropriate:

- High voltage (HV) training
- Power management system (PMS) training

- Fire and gas detection and emergency shutdowns (ESD) training
- DP control system manufacturer’s maintenance training

M117 also provides guidance on structured onboard familiarisation programs for key DP personnel, covering the steps to take to achieve, maintain and enhance competency in DP operations.

Owners/ operators may consider implementing the IMCA Competence Assurance & Assessment scheme (IMCA C002 Rev 1, 2003) which provides detailed programs for achieving and assessing the competency of key DP personnel, including vessel masters, DPOs, chief engineers and engineers in charge of a watch.

Note: Owners/ operators should also be aware of and recognise the benefits of formal training and competency programs that are currently offered by equipment suppliers, vendors and other bodies that are in excess of established industry standards, such as the Kongsberg initiative in POWERSIM training where DPOs are given training, familiarisation and exposure to a variety of power generation related faults and conditions that are known to have occurred on DP diesel electric power generation systems.

Note: Customised training programs have been developed by industry in response to client’s requests. Owners/ operators are encouraged to seek information and selectively adopt appropriate programs for their training needs.

3.29 MANNING

3.29.1 Vessels should comply with the statutory requirements for safe manning. Separately DP manning levels should be adequate for safe DP operations.

3.29.2 Owners/ operators are ultimately responsible for the competency of their DP personnel and for the safe execution of DP operations and should consider the recommendations listed below when determining DP manning levels.

Table 3-5 DP Bridge Crew

Operation	Minimum Bridge Crew per shift	Minimum Experience
When <u>undertaking critical activities</u> in proximity to surface or sub surface structures See Note 1 below	2 unlimited DPOs on the bridge capable of operating the vessel both in DP and manual control. See Note 2 below.	Unlimited DPO with a minimum of 3 years experience on a vessel engaged in similar operations, at least 6 months of which should have been on the subject or sister vessel. Experience level should be documented and auditable. See Note 3 below
Note 1	Critical activities are those activities where the consequences of equipment failure or loss of position are greater than under normal operating circumstances. For example, critical activities on a DP dive support vessel would include those occasions where the Time to Terminate is long, such as when the diver is inside a welding habitat or where the diver’s worksite is inside the conductor tubes at a production facility.	
Note 2	The Master should not be considered as one of the required unlimited DPOs for meeting the manning requirements.	
Note 3	It is recognized that in practice, given the near term market conditions owners/ operators will be challenged to meet the recommended level of experience for DPOs. Owners/ operators should recognize the associated risk from inexperienced personnel and have plans in place to address them while striving to reach the recommended experience levels.	

Engineers

There should be sufficient licensed engineers on board for all expected operations.

At least one licensed engineer should be available at all times, should be on watch during critical activities and should have at least 6 months experience on similar equipment and operations.

The engineer should be fully cognisant of DP operations, familiar with the vessel's DP FMEA document and the effects of failures of equipment relating to the position keeping of the vessel.

In DP 2 or 3 operations, the engineer should be familiar with the general philosophy of redundancy as it relates to split mechanical, electrical and ancillary systems.

Electrician/ Electrical Engineer

If required on board, an electrician should have appropriate high voltage training/certification, if applicable to the vessel. As with vessel engineers, the electrician/ electrical engineer should have at least 6 months experience on similar equipment and operations.

The electrician should likewise be fully cognisant of DP operations, familiar with the vessel's DP FMEA document and the effects of failures of equipment relating to the position keeping of the vessel.

Notes Where the minimum experience requirements cannot be met a risk based approach should be taken to determine the suitability of personnel and any additional support requirements for intended operations.

For low risk operations guidance is provided in IMCA M182. If used, the guidance provided within this document should be validated against the risks.

4 ABBREVIATIONS

AIS	Automatic Identification System
ASOG	Activity Specific Operating Guidelines
CAM	Critical Activity Mode
DGNSS	Differential Global Navigation Satellite System
DGPS	Differential Global Positioning Satellite system
DP	Dynamic Positioning
DPO	DP Operator
ECR	Engine Control Room
ESD	Emergency Shutdown System
FMEA	Failure Modes and Effects Analysis
FMECA	Failure Modes and Effects and Criticality Analysis
GPS	Global Positioning (satellite) System
IMCA	International Marine Contractors Association
IMO	International Maritime Organisation
IT	Information Technology
LBL	Long Baseline
MDAT	Mapping Delivery Ability Tool
MTTR	Mean Time to Repair
MRU	Motion Reference Unit
SIMOPS	Simultaneous Operations
SBL	Short Base Line
SSBL	Super Short Base Line
TAGOS	Thruster and Generator Operating Strategy
TAM	Task Appropriate Mode
TTT	Time to Terminate
VRU	Vertical Reference Unit
WCF	Worst Case Failure
WCFDI	Worst Case Failure Design Intent
WSOG	Well Specific Operating Guidelines

5 INTERVENTION – ROLE OF THE DPO AND ENGINEER

The notes in this section consider the role of the DPO and watchkeeping engineers, specifically addressing operator intervention in terms of the complexities of the regulatory background (operator intervention specifically addressed in Class rules) as well as operational practicalities.

Note The overriding role of the DPO in emergency situations is to stabilise the situation and to take positive action to prevent escalation.

5.1 GENERAL

5.1.1 Rules and guidelines on levels of operator intervention in response to a failure in a DP Class 2 or DP Class 3 vessel have changed over the years and different classification societies have chosen to place different levels of emphasis and different interpretations on these rules. The practical effect of this is that vessels of different ages and different class society can vary significantly in terms of the amount of operator intervention expected, allowed or required. Even in the case of DP Class 1 vessels, levels of redundancy and automation are influenced by differences in the main rules for the classification of ships.

5.1.2 Examples of the rules and guidelines that have influenced the design of redundancy concepts are given below:-

- IMO MSC 645 Section 3.1.4 states under the heading of Functional Requirements,
- General:-
 - “Redundant components and systems should be immediately available and with such capacity that the DP-operation can be continued for such a period that the work in progress can be terminated safely. The transfer to redundant components or systems should be automatic as far as possible and operator intervention should be kept to a minimum. The transfer should be smooth and within acceptable limitations of the operation.”

- DNV rules for the classification of Ships Pt6, Ch7, Sec 2 states:

- Redundancy:

“The DP-system shall be designed with redundancy. A position keeping ability shall be maintained without disruption upon any single failure. Full stop of thrusters and subsequent start-up of available thrusters is not considered an acceptable disruption.

Guidance note: Component and system redundancy, in technical design and physical arrangement, should in principle be immediately available with the capacity required for the DP-system to safely terminate the work in progress. The transfer to components or systems designed and arranged to provide redundancy, should be automatic and operator intervention should be avoided.”

“Redundancy shall be based upon running machinery. Automatic or manual intervention arranged to improve the position keeping ability after a failure will be accepted. Automatic start of equipment may be accepted as contributing to redundancy only if their reliability and simplicity of operation is satisfactory so that they can be brought into operation before position and heading keeping performance is degraded.

Guidance note: The redundancy requirements will not be considered as complied with if based upon start or restart of generators and/ or thrusters.”

The distinction between 'improving station keeping capability after a failure' and 'contributing to redundancy' should be noted. The latter is intended to mean that the contribution of this equipment or feature can be considered when defining the vessel's post WCF DP capability. The former cannot be considered when defining this capability thus DP Class 2 and DP Class 3 vessels should not operate in conditions where they would depend on this equipment to maintain position. However, the feature can be used to improve capability.

5.2 FAULTS REQUIRING OPERATOR INTERVENTION

5.2.1 The following list comprises known faults and features in DP systems that have been known to require operator intervention to prevent escalation of the failure effect or loss of position. Prudent watchkeeping practices will detect the listed events that require operator (DPO/engineer) intervention:

1. A faulty thruster may respond poorly to DP commands giving rise to a speed/ torque or azimuth prediction error. The DPO should assess the performance of the thruster and shut it down using the emergency stop if necessary.
2. Failure of a thruster to full thrust or uncontrolled rotation will require the DPO to shut the thruster down using the emergency stop. The process of identifying the faulty thruster may be made more difficult by the fact that all thrusters may be operating at high thrust to counteract the effect of the faulty one. Prediction errors may indicate which thruster is faulty.
3. A DP operator station may fail. The DPO must take control at another operator station. Note that position and heading should be maintained by the DP controller during this time.
4. Seawater cooling systems operated from a single sea chest may block giving rise to low seawater pressure alarms requiring the engineers to transfer to the other sea chest.
5. Some vessels have no automation for starting redundant pumps and engineers must monitor the condition of the plant and intervene following an unexpected stop.
6. A heat exchanger in a common freshwater cooling system may become fouled requiring the engineers to change over to another cooler. This condition may be indicated by high freshwater temperature alarms.
7. In some diesel electric designs, failures of fuel control systems or generator excitation systems can destabilise the entire plant if the vessel is operated with a common power system (busties closed). In such circumstances the engineers may open the bustie in an attempt to isolate the fault to one side or the other. A load sharing imbalance alarm may assist in identifying the onset of the fault. Note that in some circumstances the fault may escalate at a rate which precludes effective operator intervention and blackout may result.
8. A distribution system supplying a DP UPS may fail. The 'on-batteries' alarm will indicate to the DPO that certain important DP control system consumers may be lost. The DPO or ET can review the UPS distribution list against sensors, reference systems and operator stations in use to determine whether any configuration changes should be made, for example selecting the other DP controller or OS before the online controller or OS fails.
9. On some DP vessels with a single stern tunnel thruster and two main propellers which depend on the rudders to provide redundant athwartships thrust it may be necessary to transfer the tunnel thruster to the other power distribution system and restart it in the event that the distribution system supplying one main prop and the stern tunnel thruster fails.

10. On a DP Class 3 vessel, loss of the main DP station will require the DPO to take control at the backup DP station.
11. On a DP Class 2 vessel loss of both DP control systems will require the DPO to take manual control of the vessel at the independent joystick or manual control levers.
12. On vessels with two wind sensors a difference alarm may require the DPO to make an assessment of which wind sensor to use. In the case that one of the wind sensors has failed to 'high wind speed' it may be necessary to rapidly deselect the faulty wind sensor before it initiates a drive off depending on the type of DP control system.
13. On vessels with only two gyro compasses a difference alarm may require the DPO to make an assessment of which gyro to use. A faulty gyro may cause a rapid change of heading if not deselected promptly.
14. On vessels with two MRUs a difference alarm may require the DPO to make an assessment of which MRU to use.
15. DP control systems employ a range of protective functions designed to reject an errant position reference system. Class rules require that three references are in use for DP Class 2 & 3 vessels and two of the three should be based on different principles of measurement. This provides a large degree of protection against a drive off related to a position calculation error but such incidents do occur and DPOs can be expected to determine which reference systems are responsible and deselect them.
16. On vessels with a common fuel supply system, which can be found even on some DP Class 2 vessels, it may be necessary to change over a fuel filter or isolate a leak to prevent all generators being affected.
17. On some vessels with transferable thrusters, it may be necessary for the engineers to manually change over auxiliary services for the thruster even if the main supply changes automatically. This changeover, if required, is to prevent the unexpected consequences of failure.
18. DPOs should be aware of the thruster and/ or power configuration that is used to activate the Consequence Analysis alarm. It should not be assumed that it is Worst Case Failure. Where it is established that it is not WCF then steps should be taken to ensure that WCF is used as the trigger for a Consequence Analysis alarm.
19. DPO's should use the weather radar or standard radar, set up for weather, to augment their watch keeping practices to aid in proactive measures to be taken as necessary.(e.g. Squall line observed on radar- start additional generators/change heading as necessary).This is especially relevant during night time and when inclement weather is being forecast and//or being experienced.

Measures to reduce the incidence of faults requiring operator intervention

- 5.2.2 The most effective way to avoid the necessity for operators and engineers to intervene in faults is to design the redundancy concept in such a way that the need for operator intervention is minimised or preferably eliminated.
- 5.2.3 In general terms, this will often mean adding additional equipment, greater levels of redundancy, automation and increased system segregation to minimise the impact of any failure. Features such as a third wind sensor or a third DP controller allow voting or other protective functions to be used.
- 5.2.4 However, there may be some aspects of DP system design where operator intervention is preferred to any other form of response. For example, it may not be desirable to automatically transfer control location in response to a fault. It may be better for the operator to decide where control transfers to by taking control at that station.

- 5.2.5 There is also a risk that poorly designed protective functions will reduce the reliability and availability of essential equipment such as thrusters and generators. This risk should be considered when applying protective functions to deal with very low probability failure modes.
- 5.2.6 Carefully considering power plant and control system configuration can also reduce the need for operator intervention. DP Class 2 and 3 vessels should always operate in a redundant/fault tolerant configuration.
- 5.2.7 Where operator intervention in response to faults is unavoidable then it is extremely important that there are clear and unambiguous alarms and indications to alert the operators to the onset of the fault. It is also of vital importance that the required responses to the fault are documented in well-written procedures and practiced so that all DPOs and engineers are familiar with them and can take action in a confident manner.

APPENDICES

APPENDIX A REFERENCE STANDARDS/ GUIDELINES

Source	Title	Revision No. and Date	DP Operations Content
IMO	Guidelines for Vessels with Dynamic Positioning Systems	IMO MSC/Circ 645 1994	Internationally recognized basis for the design, equipment, testing, verification and operation of DP vessels
Class	Classification Society DP Equipment Rules, Survey Rules and associated rules.	ABS, DNVGL, LRS, BV, KR, etc., latest editions	DP equipment, DP operations manuals, DP trials, DP surveys, DP certification and DP class notations
USCG	Use of Dynamic Positioning (DP) by Offshore Supply Vessels (OSVs) for Oil and Hazmat Transfers	USCG D8 Policy Letter Ltr-01-2003	DP classification guidance, DP operating guidance, DP training and certification guidance
MTS	DP Vessel Design Philosophy Guidelines Parts 1 and 2	MTS DP VESSEL DESIGN PHILOSOPHY GUIDELINES (Rev2 - Jan21)	Comprehensive and detailed guidance to aid in the design of fault tolerant and fault resistant DP vessels.
MTS	PDDP2 - Guidance for Professional Development of DP Personnel	PDDP2 (Rev2 - Jan21) GUIDANCE FOR PROFESSIONAL DEVELOPMENT OF DP PERSONNEL	
MTS	High Level Philosophy	TECHOP (G-01 - Rev1 - Jan21) TECHOP PHILOSOPHY	
MTS	Power Plant Common Cause Failures	TECHOP (G-02 - Rev1 - Jan21) POWER PLANT COMMON CAUSE FAILURES	
MTS	White Paper on Continuous Trials for DP MODUs (Draft)	TECHOP (G-03 - Rev1 - Jan21) CONTINUOUS TRIALS FOR DP MODUS	
MTS	Conducting Effective and Comprehensive DP Incident Investigations	TECHOP (G-04 - Rev1 - Jan21) CONDUCTING EFFECTIVE AND COMPREHENSIVE DP INCIDENT INVESTIGATIONS	
MTS	<ul style="list-style-type: none"> • External Interfaces (Draft) • Cross Connections <p style="text-align: center;">AMALGAMATED</p>	TECHOP (D-01 - Rev1 - Jan21) ADDRESSING C ³ EI ² TO ELIMINATE SINGLE POINT FAILURES	
MTS	FMEA Testing	TECHOP (D-02 - Rev1 - Jan21) FMEA TESTING	
MTS	Blackout Recovery	TECHOP (D-03 - Rev1 - Jan21) BLACKOUT RECOVERY	
MTS	Evaluation of Protection Systems	TECHOP (D-04 - Rev1 - Jan21) EVALUATION OF PROTECTION SYSTEMS	
MTS	FMEA Gap Analysis	TECHOP (D-05 - Rev1 - Jan21) FMEA GAP ANALYSIS	

Source	Title	Revision No. and Date	DP Operations Content
MTS	DGNSS Position Reference Sensors (Draft)	TECHOP (D-06 - Rev1 - Jan21) DGNSS POSITION REFERENCE SENSORS	
MTS	A Method for Proving Fault Ride-Through Capability of DP Vessels with HV Power Plant	TECHOP (D-07 - Rev1 - Jan21) PROVING FAULT RIDE-THROUGH CAPABILITY OF DP VESSELS WITH HV POWER PLANT	
MTS	Software Testing	TECHOP (D-08 - Rev1 - Jan21) SOFTWARE TESTING	
MTS	PRS and DPCS Handling of PRS	TECHOP (D-09 - Rev1 - Jan21) PRS AND DPCS HANDLING OF PRS	
MTS	DNV RP D102 FMEA Gap Analysis	TECHOP (D-10 - Rev1 - Jan21) DNV RP D102 FMEA GAP ANALYSIS	
MTS	Redundancy Concept Philosophy Document IN PROGRESS	TECHOP (D-11 - Rev1 - Jan21) REDUNDANCY CONCEPT PHILOSOPHY DOCUMENT IN PROGRESS	
MTS	DP Operations Manual and Gap Analysis	TECHOP (O-01 - Rev1 - Jan21) DP OPERATIONS MANUAL	
MTS	Annual DP Trials and Gap Analysis	TECHOP (O-02 - Rev1 - Jan21) ANNUAL DP TRIALS AND GAP ANALYSIS	
MTS	Defining Critical Activities Requiring Selection of Critical Activity Mode	TECHOP (O-03 - Rev1 - Jan21) DEFINING CRITICAL OPERATIONS REQUIRING SELECTION OF CRITICAL ACTIVITY MODE	
MTS	Competency for DP Professionals - DP SMEs - DP FMEA Practitioners	TECHOP (P-01 - Rev1 - Jan21) PART 1, 2,3 & Addendum – COMPETENCY FOR DP PROFESSIONALS - DP SMEs - DP FMEA PRACTITIONERS	
IMCA	Guidance on Failure Modes and Effects Analysis	M166 Rev 1 2016	DP FMEA/FMECA
IMCA	Methods of Establishing the Safety and Reliability of DP Systems	M04/04 2004	DP FMEA/FMECA
IMCA	FMEA Management Guide	M178 2005	DP FMEA management

Source	Title	Revision No. and Date	DP Operations Content
IMCA	Guidelines for the Design and Operation of DP Vessels	M103 Rev 2 2016	Design philosophies, DP FMEA, redundancy, annual DP trials, checklists, DP operations, communications, manuals, manning, training, DP capability plots
IMCA	Guidance for Developing and Conducting Annual DP Trials for DP Vessels	M190 2011	Comprehensive and detailed guidance on development, conduct and management of Annual DP Trials.
IMCA	Executive Summary	M190A	Executive summary of M 190
IMCA	Guidelines of Annual DP Trials for DP MODUs	M191	Guidance specifically for DP MODUs on conducting Annual DP Trials on a continual basis throughout the year.
IMCA	Example of an Annual DP Trials Report	M212 2011	Guidance on reporting annual DP trials, including independent witness competency
IMCA	Example Specification for a DP FMEA for a New DP Vessel	M219 2012	
IMCA	Example Redundancy Concept and Annual DP Trials for a DP Class Construction Vessel	M225 2014	
IMCA	A Guide to DP Related Documentation for DP Vessels	M109 Rev 2, 2016	DP operations manual – TOC, DP documentation, vessel operations manual, planned maintenance
MSF	International Guidelines for the Safe Operation of DP OSVs ¹⁶	MSF M 182 Rev 2, 2015	DP FMEA, annual DP trials, checklists, manning, DP capability plots, incident reporting and investigation, risk based approach to DP operations
IMO	Guidelines for Dynamic Positioning (DP) Operator Training	IMO MSC/738 Rev 1, 2006	Internationally recognized guidance for DPO training and experience
IMCA	The Training and Experience of Key DP Personnel	M117 Rev 1, 2006	Training, experience and certification requirements, onboard Familiarisation for key DP personnel
Nautical Institute	The Nautical Institute Dynamic Positioning Operator's Certificate	January 2010 Revision	Detailed guidance on the implementation of NI's internationally recognized DPO certification scheme
IMCA	Station Keeping Incident Form for DP Vessels	2008	Incident report form for DP vessels (DP construction, OSVs, etc.)
IMCA	Station Keeping Incident Form for DP Tankers, FPSO, etc.	2006	Incident report form for DP tankers, FPSOs, etc
IMCA	DP Incident Reports – Annual Summary and Analysis – all years	1994 - onwards	Useful analysis and summary of DP incidents submitted to IMCA by member company vessels
IMCA	Specification for DP Capability Plots	M140 Rev 1, 2000	DP capability plots, worst case failure

¹⁶ Formerly issued as IMCA M 182 this guidance document is now known as MSF M 182. It is published by IMCA on behalf of the Marine Safety Forum (MSF).

Source	Title	Revision No. and Date	DP Operations Content
IMCA	Guidance on Simultaneous Operations	M203 2010	Simultaneous operations
IMCA	Guidance on Operational Communications	M205, D046 2010	General guidelines, diving operations, lifting operations
IMCA	Guidelines for Annual DP Trials for DP Mobile Offshore Drilling Units	M191 2008	Annual DP trials, guidelines for incremental annual DP trials
IMCA	Common Marine Inspection Document (CMID)	M 149 Issue 9 2015	
IMO	International Safety Management (ISM) Code	ISM Code 2015	International standard for the safe management and operation of ships and for pollution prevention

APPENDIX B DP FOOTPRINT PLOTS – WORKED EXAMPLES

Worked Example 1

Date: 22 Sept 2010 Time: 1055 hrs
 Location: 60° 45'N 2° 30'W DP Operator: A. Smith

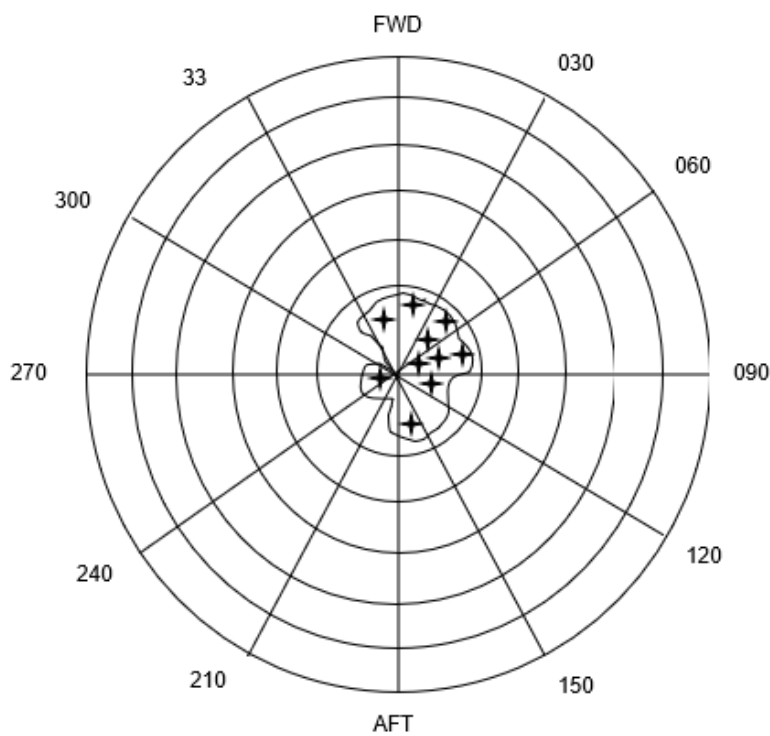
DP FOOTPRINT PLOTTING SHEET

Position Refs

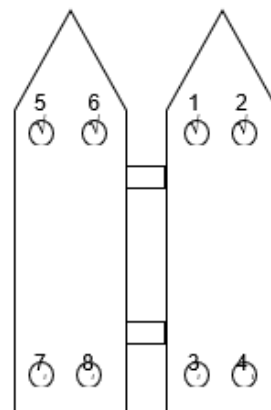
- DGPS 1 ✓
- DGPS 2 ✓
- HiPAP 1 ✓
- HiPAP 2 ✓

Environment

- Wind Dir'n 225° (direction from)
- Wind Speed 45 – 50 kts
- Wave Period 7 secs
- Wave Height 6 m
- Current Dir'n coincident 225°
- Current Speed 1 kt



Vessel:
 Heading: 000° (North) Water Depth: 140 m
 Draft: 20 m Rate of turn: 10deg/min
 Speed of Move: 0.3m/sec Scale: 1 div. = 2 Meters



- Thruster 1 45%
- Thruster 2 43%
- Thruster 3 49%
- Thruster 4 50%
- Thruster 5 45%
- Thruster 6 45%
- Thruster 7 48%
- Thruster 8 46%

Worked Example 2
1110 hrs

Date: 22 Sept 2010 Time: 1110 hrs
 Location: 60° 45'N 2° 30'W DP Operator: A. Smith

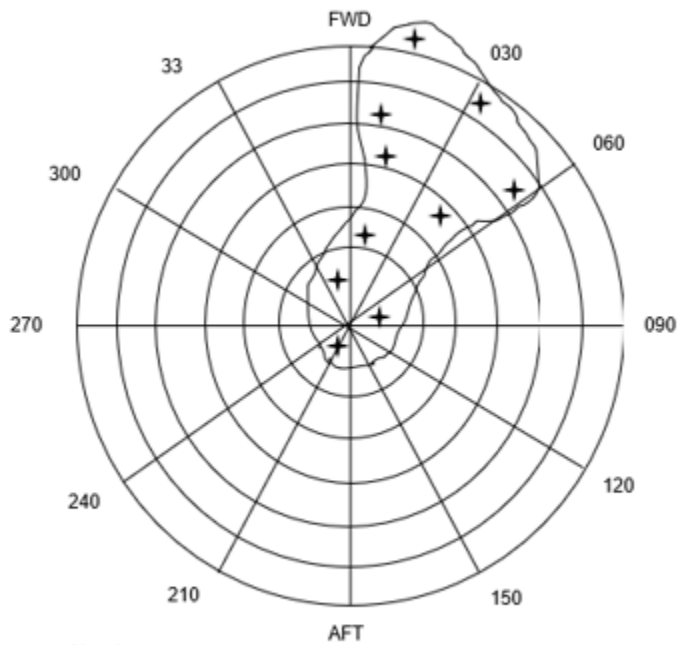
DP FOOTPRINT PLOTTING SHEET

Position Refs

- DGPS 1 ✓
- DGPS 2 ✓
- HIPAP 1 ✓
- HIPAP 2 ✓

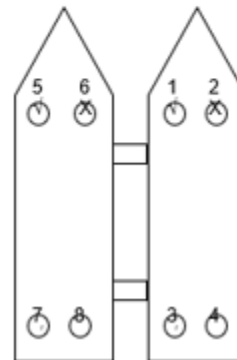
Environment

- Wind Dir'n 225° (direction from)
- Wind Speed 45 – 50 kts
- Wave Period 7 secs
- Wave Height 8 m
- Current Dir'n coincident 225°
- Current Speed 1 kt



Vessel:
 Heading: 000° (North)
 Draft: 20 m
 Speed of Move: 0.3m/sec

Water Depth: 140 m
 Rate of turn: 10deg/min
 Scale: 1 div. = 2 Meters



- Thruster 1 100%
- Thruster 2 100%
- Thruster 3 100%
- Thruster 4 100%
- Thruster 5 100%
- Thruster 6 100%
- Thruster 7 100%
- Thruster 8 100%

APPENDIX C ANNUAL DP TRIALS TEST TABLE BLANK – DP MODU

Guidance Note
PLEASE REFER TO IMCA M 191

APPENDIX D EXAMPLE OF CAM AND WSOG

EXAMPLE OF A CAM				
CRITICAL ACTIVITY Mode (CAM) of Operation - Name of DP Drilling Rig				
This setup applies when the vessel is undertaking DP Drilling Operations. AFI (agreed for implementation)				
DATE				
Critical operations are when the vessel is having non shearables through the stack.				
Condition	GREEN	ADVISORY		
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES		
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)		
Power Distribution	11kV Bus Interconnectors A-B; C-D closed; B-C; A-D open All 480V bus Interconnectors open	Any of 11kV bus interconnector A-B; C-D open or A-D; B-C closed. Any 480V bus interconnector closed		
Diesel Generators	Tested at 100% within the last 6 months	Not tested at 100% within the last 6 months or problems found		
Diesel Generators	At least one generator on each bus bar	Any section running thrusters without at least one generator		
Diesel Generator MCC's	All supplied from respective main 480V	Any supplied from ESB 480V		
LVE and LVF (low voltage swbds E & F)	Auto changeover to 'A' or 'B' and 'C' or 'D' tested at field arrival	Not tested or problems found		
HRG earth (high resistance ground)	Not tripped and only one connected per isolated section of Bus	Tripped or more than one connected		
Thrusters	Tested at 100% on field arrival	Not tested at 100% on field arrival or problems found		
Thruster Hydraulic steering pump (critical operations)	All thrusters duty pump set to MCC 'A'	Any duty pump set to MCC 'B'		
Thruster Hydraulic steering pumps changeover	Tested on field arrival	Not tested on field arrival or problems found		
Thruster Emergency Stops (Bridge)	Tested on field arrival	Not tested on field arrival or problems found		
Power Management System	Automatic Generator stop disabled	Any other set up		
Power Management System (Critical Operations)	Fixed Load mode not selected	Any generator selected to Fixed load mode		

Condition	GREEN	ADVISORY		
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES		
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)		
Power Management System	Load share in (isochronous mode/droop mode) as deemed appropriate for vessel) Note to be determined based on vessel design)	Load share failed to mode other than appropriate mode		
Power Management System	Blackout restart enabled	Blackout restart disabled		
DP and VMS UPS's; 24VDC and 110VDC systems	All connected to their respective 480V supply and back up changeover tested at field arrival	Any UPS connected to the emergency switchboard, failed or on bypass		
UPS and 24VDC and 110VDC Systems	Batteries tested on load on field arrival	Not tested on field arrival or problems found		
24V and 110VDC systems	Tested on field arrival to ensure no diode failures	Not tested on field arrival or problems found		
DP Control System	Consequence analysis enabled and not in alarm	Any other set up		
DP Control System	Kalman gains set to 0 (1 if acoustic update > 4 seconds)	Any other Kalman gain		
Back Up DP	Transfer of control tested at field arrival	Transfer not tested or known problems		
DP Reference System	Median Check set up and enabled, with agreed references	One of the agreed references unavailable		
Position References Available	Four references selected and enabled (2 DGPS and 2 LBL). DGPS 1 <u>or</u> 2 <u>and</u> DGPS 3 <u>and</u> LBL 1 <u>and</u> LBL 2	Less than three references available, or both DGPS 1 <u>and</u> 2 selected		
Position References Available	Both Acoustics (LBL) dedicated to DP control	Acoustics also being used actively by survey or others		
DGPS	Systems on different differential systems and elevation masks	Any other set up		
Acoustics	Frequencies in use planned with other DP vessels in the area	Not planned		

Condition	GREEN	ADVISORY		
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES		
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)		
Acoustics	If both Acoustics in use, interfaced to alternative MARHS	Both Acoustics using same MAHRS		
Placement of targets for OSV's	Redundant targets placed at optimum locations suitable for diverse relative position reference systems on board OSV's (CyScan, Fanbeam, RadaScan, Radius)	Single targets or obscured or poorly sited. Only one type installed.		
Fuel Systems	Purifier gravity discs matched Strict anti-contamination procedures in practice	Any other set up		
Main Engine SW cooling	Each main pump fed from its own sea chest.	Any main pump fed from the adjacent sea chest.		
Main Engine SW cooling	Port and stbd system isolated from each other	Port and stbd systems common.		
Electric' SW Cooling	Valves VELXXX and VELYYY closed. Valves VELZZZ and VELAAA open	Any other set up		
Electric' SW Cooling	Changeover of Duty/Standby pump tested at field arrival	Changeover of Duty/Standby pump not tested on field arrival or problems found		
Electric' FW Cooling	Standby start function of cooling pumps tested at field arrival.	Standby start function of cooling pumps not tested at field arrival or problems found.		
Start air	4 compressors available. 2 receivers isolated port/stbd cross connection isolated	less than 4 compressors available or all receivers on line or cross connection open		
ESD	Life boat station ESD's disarmed	Life boat station ESD's armed		
Air Conditioning to all DP critical areas	All AHU's running & changeovers tested recently for cooling pumps and compressor units	Any AHU off or changeover not recently tested or any HVAC alarm		
Engine Room Manning	ECR Manned by qualified Engineer	ECR not Manned or engineer not qualified		

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
Maximum Watch Circles Radius (From Well Head position) <1 year condition (<=Wind 41 knots, current 0.7 knots, Hs 16ft)				39m
Maximum Watch Circles Radius (From Well Head position)- > 41 knots, current 0.7 knots Hs 16 ft and collinear				Immediately if blackout occurs (Dictated by riser analysis)

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
Colinearity (1 year winter storm)	If wind < 30 knots and current is less than 0.5 knots and colinearity > than 15 deg	If Wind is >30 knots and current is >0.5 knots and colinearity within 15 deg	If wind approaching 41 knots and current is approaching 0.7 knots and colinear	
Colinearity (loop current)	If wind < 15knots and current is less than 1.5 knots and colinearity > than 15 deg	If Wind is >15 knots and current is >1.5 knots and colinearity within 15 deg	If wind approaching 19 knots and current is approaching 2 knots and colinear	
Weather Forecast	Within Post WCF Operating limits	Approaching Post WCF operating limits	Exceeding Post WCF operational limits	

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
DRIVE OFF or	All systems operating correctly	Discrepancy in PRS. Inexplicable ramp up of thrusters	Immediately when recognized by DPO	Unable to control Drive Off
DRIFT OFF				
Drilling offset from well head position	Position directly over wellhead	Any offset from ZAP	=/>12.m	
Heading excursion	No Heading Alarms or warning	If heading warning limit reached (>3 degrees)	If heading Alarm limit reached (>5 degrees) or Heading instability with frequent alarms	

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
Vessel Footprint/Weather related excursion (From Set point)	No position alarms or warning	If warning position limits reach (>3m)	If Alarm position reached (>5m) or Position instability with frequent alarms	
Drape Hose Heading Limitation	> -200 ° < +200 °	+/-200 to 240°	> -240 ° < +240 °	To be established at Field Trials
Long Turn		Being considered	Under execution	
Riser Limitation (UFJ)	0 - 2°	>2 °	>4 °	
Riser Limitation (LFJ)	0 - 2°	>2 °	>4 °	

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
'Power Trains'/Thrusters in use	At least two diagonally opposite pairs of thrusters running and selected to DP (1 thruster in each corner)	Any selected thruster in alarm	Less than two diagonally opposite thruster pairs running and selected to DP	
Thruster loading (thrust)	all <values given in generator configurations and limits document	any approaching values given in generator configurations and limits document	All > values given in generator configurations and limits document	
Any change in thrusters/propulsion in or out of use		Advisory		

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
Diesel Generator Loads	All generators available with at least one generator on line on each bus, generators usually symmetric configuration. Generator configuration as per TAGOS if available	Power consumption >= power demand required to maintain position following WCF (usually loss of one Switchboard/ loss of one E/R) Or values in TAGOS document	Power demand > 65% for duration of one minute with maximum number of generators on line Or values as described in TAGOS document	
Any change in generators in or out of use		Advisory		

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
Thruster phase back, drilling phase back or DP control system power limiting	No Alarm	Approaching operating limits	Alarms and or phasing back or limiting	-
DP UPSs and 24 VDC Systems	Main and back up supply available no UPS in by pass. No UPS alarms	Any UPS in bypass or in alarm	Main supply cannot be reinstated or total UPS failure	
DP Control System	Power mimic information correct	Any wrong information	Critical information wrong or DP is in power limit	
DP Control System	Triplex	Any 1 CC Controller failed	Any 2 CC Controllers failed	

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
DP Network	Dual	Any alarms or poor performance	1 network lost	Complete loss of networks
VMS/PMS Controllers	Dual	Any alarms or poor performance	1 Controller failed	
Position References Available	Four references selected and enabled (2 DGPS and 2 LBL). DGPS 1_or 2_and DGPS 3_and LBL 1_and LBL 2	Three references available, or both DGPS 1_and 2 selected	Only two references available or One system(no redundancy in system - i.e. DGPS only or Acoustics only)	

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots	POD 4.1%, Time to POD 142 s			
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots	POD 10%, Time to reach POD 352 s			
For Total EDS(disconnect sequence) and unlatch time XX s	Red watch circle at 39m	Based on mud weight aa ppg; top tension cccc kips		
Motion sensors (MRU/VRU) into DP	3 or 2 MAHR/MRU	1 MAHR/MRU or difference alarm	loss of all MAHR/MRU	
Heading Sensors (Gyro)	3 Gyros	2 Gyros	1 remaining Gyro	
Wind Sensors	3 or 2 wind sensors	1 wind sensor	No sensor and Gusty conditions	
Loss or problem with any essential Communications (DP / ECR / Driller / ROV)	Redundant Communications	One system remaining	No comms	-
Engine Room(s) Ventilation	Full ventilation	Any reduced ventilation	Complete loss of ventilation resulting in power reduction	

EXAMPLE OF A WSOG – XXX WELL/LOCATION NAME				
Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Driller, Master, Chief Engineer, Rig Superintendent, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES (Prepare for disconnect)	INITIATE EDS (disconnect sequence)
Water Depth XXXX m				
Emergency Disconnect Time XXs	The Emergency Disconnect time is to be established from field trials. If the time is measured by a surface test, 10 seconds is to be added for conservatism. (Note There may be more than one EDS time. Appropriate one to be used for activity)			
The Red watch circle below is to be established from calculated drift off curves at 1 year environment, defined Point of Disconnect (POD) and the measured EDS (disconnect sequence) time. If environmental conditions are in excess of the 1 year environment and a blackout occurs, a Red status is to be issued immediately.				
From FMEA proving trials, blackout restart time was established at around 1minute 30 seconds from blackout to recovery of all thrusters				
1 Year Winter storm is 41 knots of wind, Hs 16 feet, Surface current is 0.7 knots		POD 4.1%, Time to POD 142 s		
10 Year Winter storm is 50.5 knots of wind Hs21.7 ft, Surface current is 0.86 knots				
10 year Loop current is 19 knots of wind, Hs 6 ft; current is 2.2 knots		POD 10%, Time to reach POD 352 s		
For Total EDS(disconnect sequence) and unlatch time XX s		Red watch circle at 39m Based on mud weight aa ppg; top tension cccc kips		
Air Conditioning to Critical Equipment	Full Air Conditioning	Any reduced Air Conditioning or frequent alarms (initiated from ECR)	Reduced Air Conditioning affecting critical equipment	
Starting Air	4 compressors available	Any compressor in alarm or not available	Any loss of start air	
Fire - E/R or elsewhere	No fire , no fire alarms	Any fire alarm	Fire Confirmed	-
Flood	No bilge alarms active, no flooding	Multiple bilge alarms	Flood Confirmed	-
Collision	No collision imminent / minimum approach >500m	Minimum approach will be < 500m	If collision possible	Collision Imminent

SIMOPS - Well Specific Operating Guidelines - Name of DP Drilling Rig				
Condition	GREEN	ADVISORY	YELLOW	RED
Notify Other vessels in the field, Driller, Master, Chief Engineer, Rig Manager, Toolpusher and Client	NO	YES	YES	YES
Action	CONTINUE NORMAL OPERATIONS	INFORMATIVE/CONSULTATIVE STATUS (RISK ASSESS)	HALT OPERATIONS AND INITIATE CONTINGENCY PROCEDURES	INITIATE EDS(disconnect sequence)
Change from Green DP Status of any other vessel in the field	Green	Advisory	Advisory	Advisory
Comms/interaction with other vessels	Vessels operating normally with no known problems	Comms problem or escape route compromised	No comms or escape route compromised	

Notes:

1. This document shall be followed as closely as possible during DP Operations.
2. Escape Route to be established.

Signed:

On behalf of
Owner/Operator

Printed name

On behalf of Client

Printed name
